RENNCO, INC. PACKAGING MACHINES AND SYSTEMS P.O. BOX 116 23721 M-60 WEST HOMER, MICHIGAN 49245 (517) 568-4121

THIS MANUAL APPLIES TO PACKAGERS WITH HEATED BACK-UP STYLE "SHRINK" OR TYPE "SF" JAW ASSEMBLIES. AND SPECIFICALLY FOR EQUIPMENT WITH THE FOLLOWING SERIAL NUMBERS:

ITEM	MODEL	SERIAL NUMBER
Packager	101	JR1420S2119GN
		,
	·	

101 GN 201 FL

401 AP

501 AC

CODE: HBSHRINKMAN1, HBSHRINK.MAN2

FORWARD

Your Rennco Packaging System has been designed, and tested to obtain the best results for your particular product and application. Its performance depends on proper use and care. For this reason please take the time to read through and understand the information in this manual before attempting to set up or operate the equipment.

As with all machinery containing moving parts, it is important to pay particular attention to all information in this manual, and labels on the machinery that contain safety warnings and cautions.

This manual is assembled in "UNITS" that follow a logical progression. Machine and packaging film specifications, requirements before installation, and component identification illustrations are given in $\underline{\text{UNIT}}$ $\underline{\text{A}}$.

<u>UNIT</u> B details procedures before actual start up of the machine, and <u>UNIT</u> C describes the initial set up steps of adjusting heat, loading film, adjusting jaw safety function, and threading trim tail.

<u>UNIT</u> <u>D</u> deals with adjustment and set up procedures in depth.

Particular attention should be paid to <u>UNIT E</u> which contains <u>SAFETY WARNINGS</u>.

Rennco welcomes the opportunity to serve you in every way that we can. If questions arise, feel free to contact us.

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UNITA GENERAL INFORMATION

SECTION 1 INSPECTION, WARRANTY, PARTS ORDERING INFORMATION REQUIREMENTS BEFORE INSTALLATION

- 1.1 INSPECTION Your Rennco Packaging System has received a thorough inspection before shipment. At time of delivery, please inspect all containers for any concealed damage or shortage. If damage is evident, note this on all freight bills and have the delivering driver sign. File a claim with the carrier as they are responsible for any damage that occurs in shipment. For Rennco's records, and so that we may assist you in every way possible, please notify us as soon as possible.
- 1.2 <u>LIMITED WARRANTY</u> The basic warranty of your Rennco Packaging Equipment is for a period of 6 months, exclusive of purchased components which are covered by the manufacturer's warranty. Rennco warrants all parts it manufacturers to be free of defects in material and workmanship for a period of 6 months to the original owner. Parts found to be defective will be replaced free of charge. Labor incurred in removing or installing the defective part is not covered by this warranty.
- 1.3 PARTS ORDERING INFORMATION When requesting information on parts or general assistance, it is important to give the model number and serial number of the equipment. This can be obtained from the specification page of this manual or from the nameplate mounted on the front upright plate of the packager, or the side panels of conveyors and optional equipment.
- 1.4 <u>REQUIREMENTS</u> <u>BEFORE</u> <u>INSTALLATION</u> After completion of the following items, the machinery can be installed by a Rennco Service Representative. Call (517) 568-4121 and request the service department for scheduling of installation. Allow 1 to 2 weeks after call for installation date.
 - **Have proper packaging films on hand at time of installation.
 - **Have adequate product available for packaging to simulate actual production.
 - **Have personnel that will later be responsible for the system's operation and maintenance available during the installation.
 - **For details of requirements for air and electric service, see the following packager specification sheet that applies to your machine and UNIT B, SECTIONS 2 AND 3.

SECTION 2.1 MACHINE SPECIFICATIONS

	MODEL 401	33" (83 cm)	51" (130 cm) 60" (153 cm)	32" to 46" (81 cm to 117 c		950 lbs. (432 1400 lbs. (637 1100 lbs. (500
	MODEL 501-36	37" (94 cm)	51" (130 cm) 62" (158 cm)	34" to 48" (86 cm to 122 cm)	AND PRODUCT	(477 kg) 1050 lbs. (477 kg) (704 kg) 1550 lbs. (704 kg) (613 kg) 1350 lbs. (613 kg)
LOATTONS	MODEL 501		73" (185 cm) 62" (158 cm)	34" to 48" (86 cm to 122 cm)	PACKAGING MATERIAL	1050 lbs. (477 kg) 1550 lbs. (704 kg) 1350 lbs. (613 kg)
SECTION 2.1 MACHINE SPECIFICALIUNS	MODEL 101	cm)	41" (104 cm) 62" (158 cm)	34" to 48" (86 cm to 122 cm)	RAINUTE DEPENDING ON PACKAGING MATERIAL AND PRODUCT	550 lbs. (250 kg) 800 lbs. (363 kg) 600 lbs. (272 kg)
SECTI	MODEL 201	37" (94 cm)	30" (76 cm) 56" (142 cm)	33" to 44" (84 cm to 112 cm)	5 to 60 PACKAGES PER	350 lbs. (159 kg) 600 lbs. (272 kg) 400 lbs. (181 kg)
	MACHINE DIMENSIONS:	WIDTH OVERALL	DEPTH OVERALL HEIGHT OVERALL	PRODUCT LOAD HEIGHT:	PACKAGER CYCLE SPEED:	APPROXIMATE WEIGHT: MACHINE ONLY EXPORT CRATED-OCEAN EXPORT CRATED-AIR

cm)

кв) кв) кв)

SEAL DIMENSIONS:	201 STD.	201 PP	101 STD.	101 PP			
MAXIMUM VERTICAL SEAL	8" (20 cm)	8" (20cm)	14" (36cm)	10" (25cm)	8" (20 cm) 8" (20cm) 14" (36cm) 10" (25cm) 18" (46 cm)	18" (46 cm)	14" (36 cm)
MAXIMUM HORIZONTAL SEAL 10" (25 cm) 10" (25cm) 20" (51cm) 18" (46cm)	10" (25 cm)	10"(25cm)	20"(51cm)	18"(46cm)	52" (132 cm)	36" (92 cm)	36" (92 cm)
MAXIMUM PRODUCT THICKNESS 3½" (9cm) 3½" (9cm) 4½"(11	3½" (9cm)	3½" (9cm)	4½"(11cm)	1cm) 4½"(11cm)	4½" (11 cm)	9½" (24 cm)	5½" (14 cm)
MINIMUM PACKAGE SIZE	x1	1" (2.5 c	1" x 1" (2.5 cm x 2.5 cm)				

YOUR PACKAGER:

NUMBER
SERIAL

AMPS AT ELECTRICAL

50/60 HZ ı VOLTS A.C.

- PH

AIR USAGE

P.S.I. S.C.F.M. PER MACHINE CYCLE AT

UNIT A GENERAL INFORMATION

SECTION 2 MACHINE SPECIFICATIONS, RECOMMENDED MATERIALS

2.2 RECOMMENDED PACKAGING MATERIALS

Centerfolded film roll dimensional requirements:

*3" I.D. core

*12" maximum O.D.

*Film roll width should include the package width plus 1 to 1 1/2 inches for the required trim take-up

*"A" wind film is recommended; however, the packager is capable of running "B" wind film.

Polyethylene films in either low density, high density or linear low density types can be sealed on Rennco packagers equipped with the type "SF" sealing assembly. The film should be made with virgin resins and contain 3 to 5 percent "EVA".

Oriented shrink films are run on packagers equipped with "shrink" type sealing assembly. The following types of film may be sealed on this type of sealing assembly:

*DUPONT - Clysar XEH921, Polyolefin Clysar EHC, Polypropylene

*W. R. GRACE - Cryovac D955, Polyolefin Cryovac MPD, Polypropylene

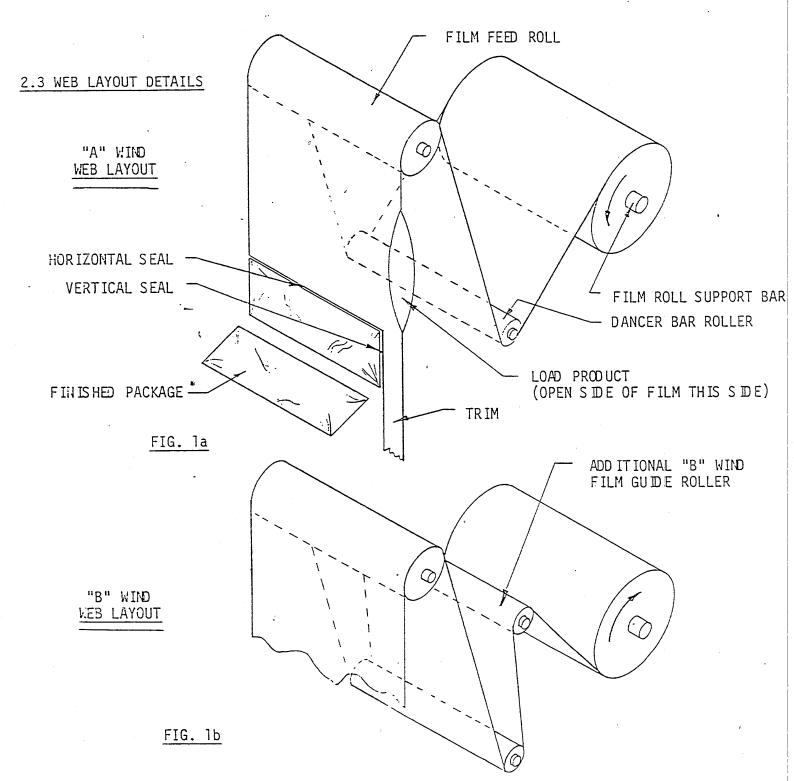
The construction of shrink and type "SF" sealing assemblies is similar but different types of films may require different temperatures, different sealing blades or different back-up materials.

In most cases, running shrink film requires the use of shrink trim take up instead of the standard trim wind up assembly.

Usually film can be supplied by your Rennco representative or he can recommend where it can be purchased in your area.

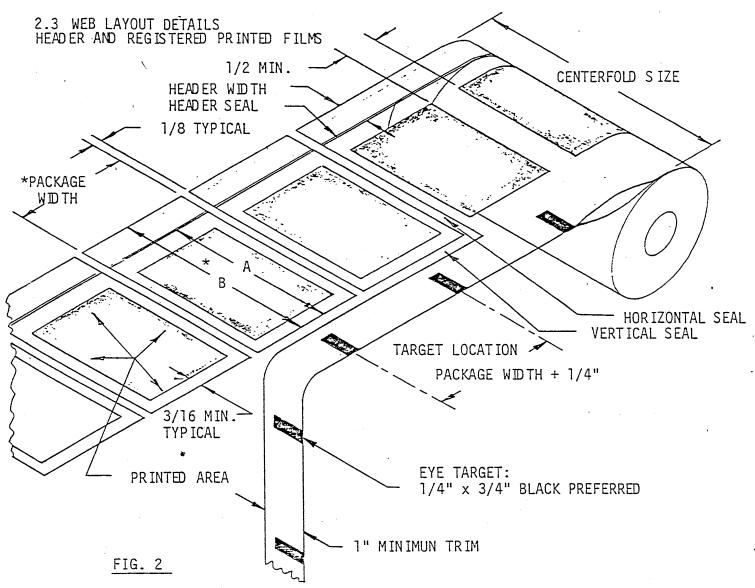
Refer to the following diagrams for additional film specifications and web layouts.

UNITA GENERAL INFORMATION SECTION 2



NOTE: As viewed from the open edge of the film roll, if the film roll spins counterclockwise as the web is pulled from the roll it is "A" wind film, if it spins clockwise it is "B" wind film.

SECTION 2 RECOMMENDED PACKAGING MATERIALS



NOTES

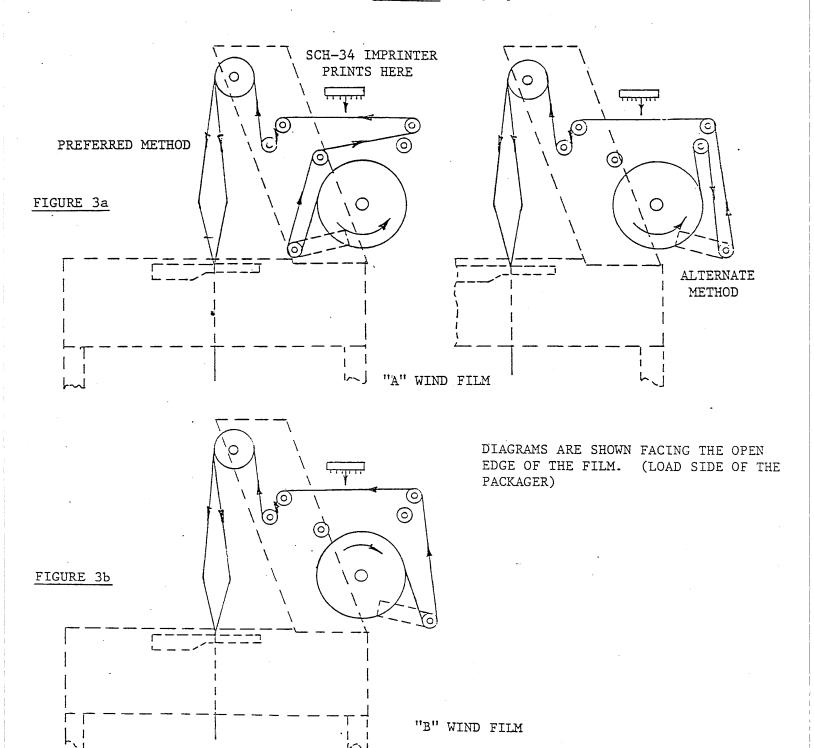
- * Shows package size not product dimension
- A Actual package length when header material is used
- B Package length if not header material
- C Header width usually ranges between 1" and 2". This dimension is to be added to overall bag length.

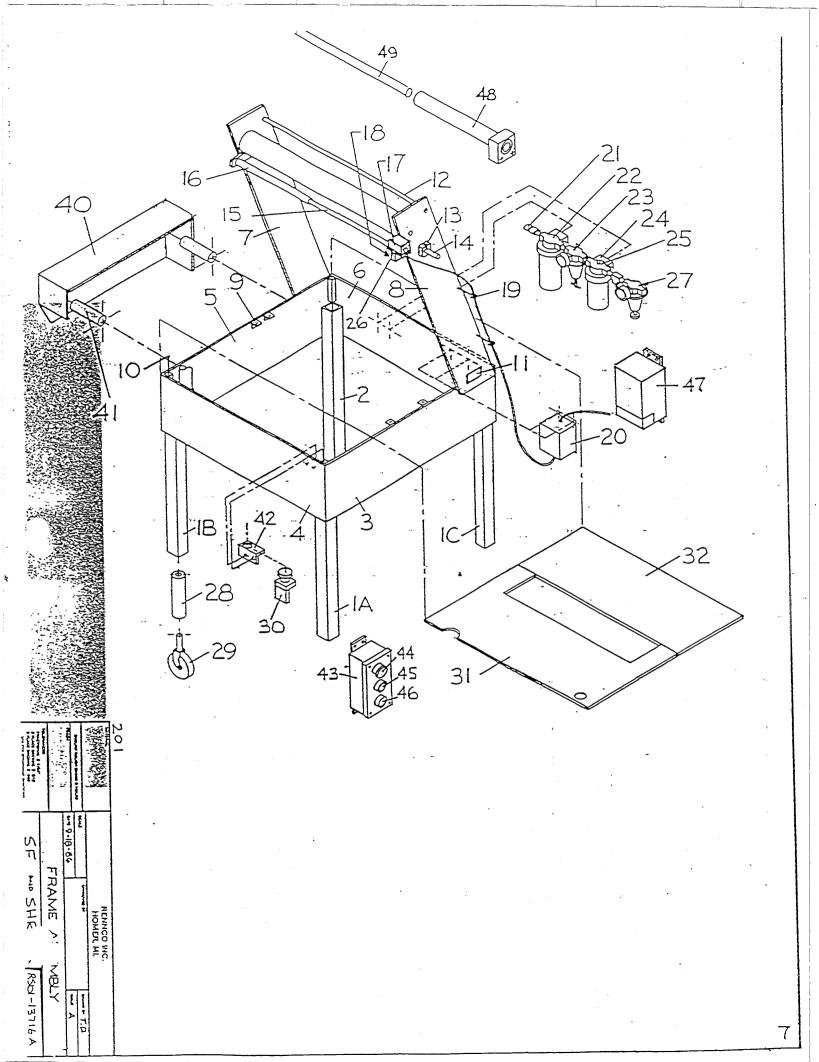
SECTION 2 RECOMENDED PACKAGING MATERIALS

2.3 WEB LAYOUT DETAILS

WEB LAYOUT FOR PREPRINTED FILM/SCH-34 IMPRINTER COMBINATION

- 1. The film must be preprinted on this side if the added SCH-34 Imprinter matter is to be on the $\underline{\text{same}}$ side as the preprinted matter.
- 2. The film must be preprinted on this side if the added SCH-34 Imprinter matter is to be on the side opposite the preprinted matter.

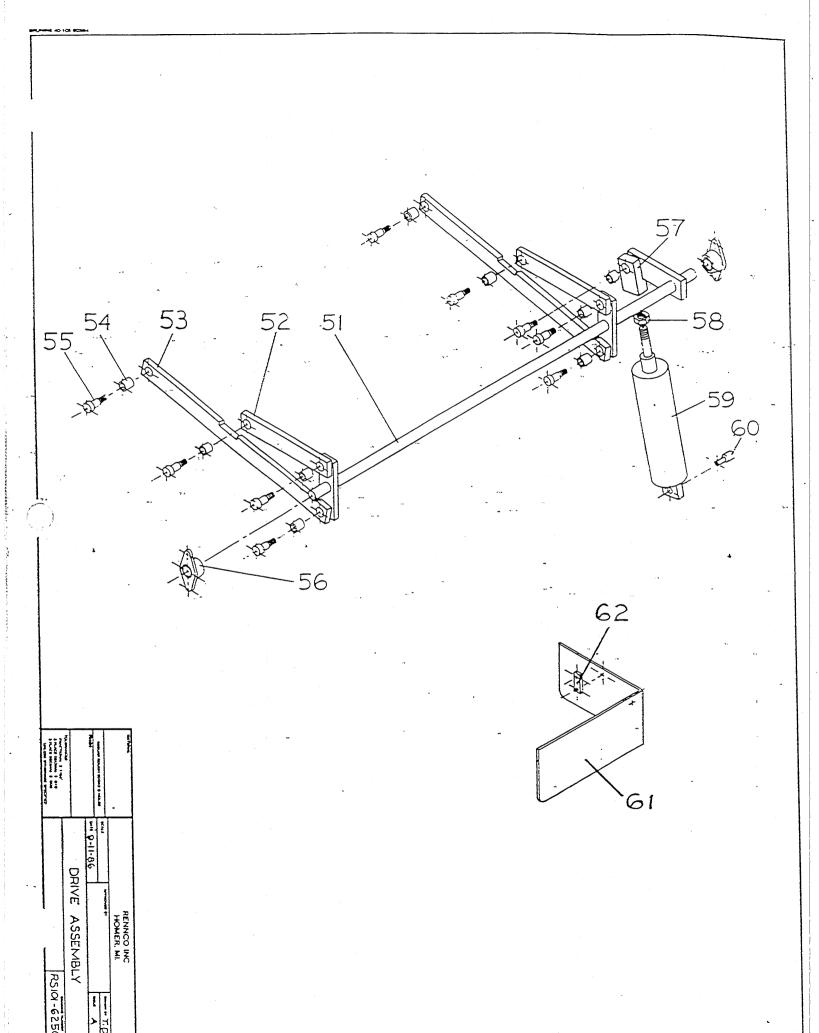




SHRINK & S.F. WITH BACK-UP HEATER 101

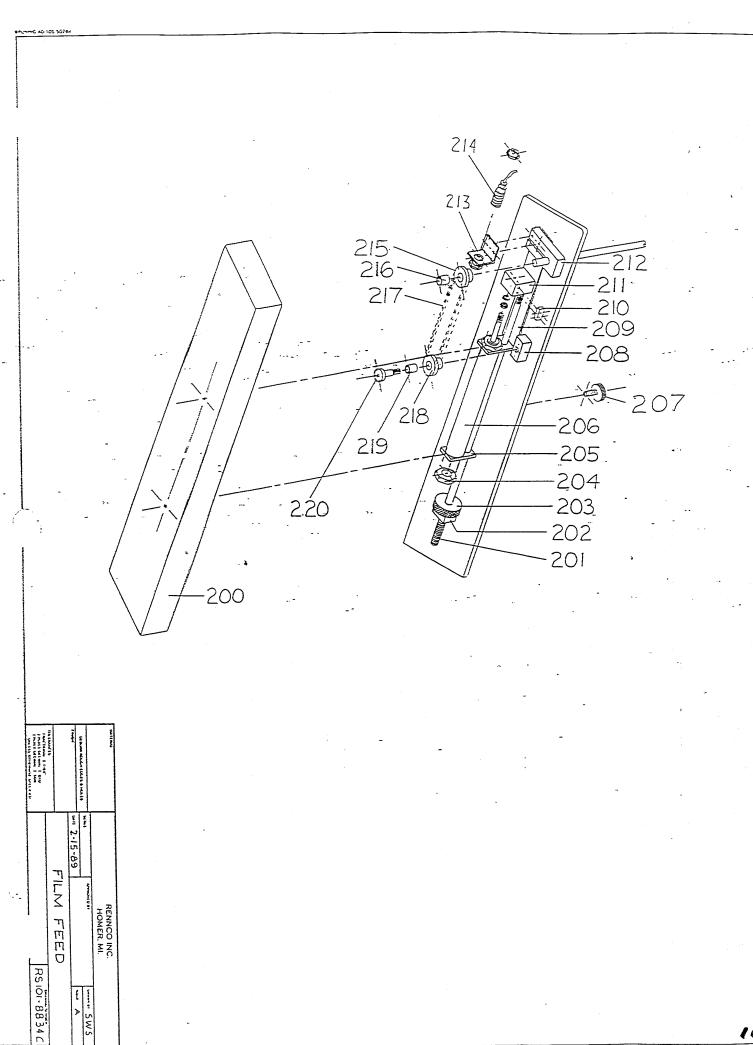
FRAME ASSEMBLY - 101

ITEM#		PART#	ISSUE		TY.
1B,C		R101-608B P1	C		2
iA		R101-608B P2	C	L.H. FRONT LEG	1
2 3		R101-610B	<u>C</u>	R.H. REAR LEG	1
		R101-594C	E	FRONT PLATE	1.
4		R101-5950		L.H. SIDE PLATE	1.
5 6		R101-593C		BACK PLATE	1
7		R101-596C	J	R.H. SIDE PLATE	1
8		R101-592C R101-479C	G K	BACK UPRIGHT	1
9		R101-114A	r B	FRONT UPRIGHT	1.
10		R101-569A	a A		4
11		LABEL	!" !		4
12		R101-602A	A	RENNCO NAME PLATE UPRIGHT SUPPORT	1
13		R101-705A	B		1
14		R101-706A	n R	FILM SEPARATOR MT. BLOCK FILM SEPARATOR ROD	1
15		MEJ15	A.	18" SIMCO STATIC BAR	1.
16		NOT USED		TO OTHER DHK	1
17		RS101-10113A	Α	STATIC ELIMINATOR BAR CLAMP	• •
18		RS101-10111A	A	STATIC ELIMINATOR BAR MTG. BRKT.	4-1
19					3
20		F167		SIMCO TRANSFORMER	1
21		T08-000-E1P0	*	NORGREN SHUT OFF VALVE	1
22		F08-000-A3D0			1
23		R08-000-RGM0		NORGREN REGULATOR W/GAUGE	1.
24		5302-06			2
25		L08-000-MPD0		NORGREN LUBRICATOR	1
~ .? \$		RS101-10112A	A	STATIC ELIMINATOR BAR MTG. PLATE	1
/7	×	R08-000-RGF0		1 1 Mt. 175, Mt. 176, Mt. 176 1 Mt.	1
28		R401-083B	B	LEG EXTENSION & CASTER MT.	4
/29		TP5250-12-SR-E	!	CASTER	Ą
/30		PW3M32		MICRO-SWITCH MUSH. HD. P.B.	1
/		PW3CD		A	1
31		R101-597C	E Si	L.H. TOP PLATE	1
32		R101-598C	Č %	Ŗ⊊H. TOP PLATE	1
33					
34					
35					
36					
37			ŧ		
38 39			· ***		
39 40		* The state of the			
40 41	4	R101-758C		VALVE COVER	1
42		R101-760A R101-1067B	A O	VALVE COVER SPACER	2
43		NOT USED	A	CYCLE SW. MOUNT BRKT.	j.
44		NOT USED			
45		NOT USED			
-75 46		NOT USED			
47		NOT USED			
48		NOT USED			
49		NOT USED			
		e a last de la last faut base diet			



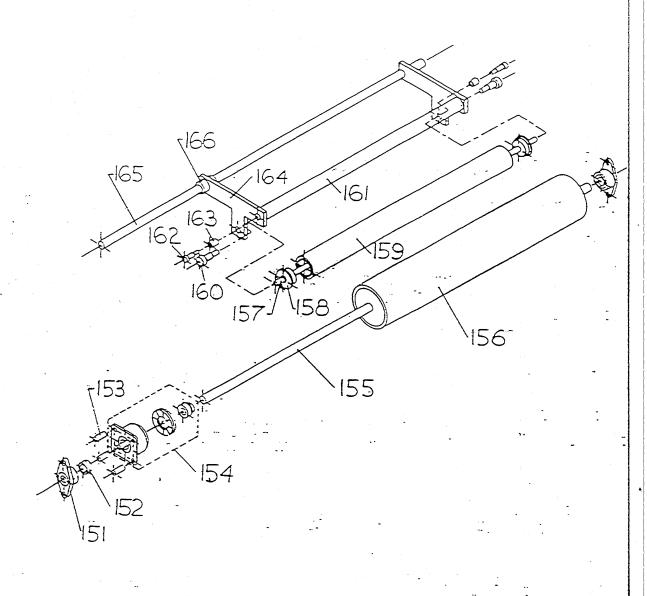
DRIVE - 101

ITEM#	PART# ISSUE	DESCRIPTION		QTY.
51	R101-557B C	TRANSFER SHAFT WELDMENT		1.
52	R101-018A E	TOP PIVOT ARM		2
53	R101-019A F	BOTTOM PIVOT ARM		2
54	B1010	TORRINGTON NEEDLE BEARING	j	9
55	SHSS23	VLIER SHOULDER BOLT		9
56	LT1624-16	MASTEN BEARING		2
57	R:101-394A A	JAW DRIVE CLEVIS		1
58	5/8-11	JAM NUT		i
59	0420-1009-050	ARO CYLINDER		1.
60	NOT USED			
61	NOT USED			
62	NOT USED			



FILM FEED - 101

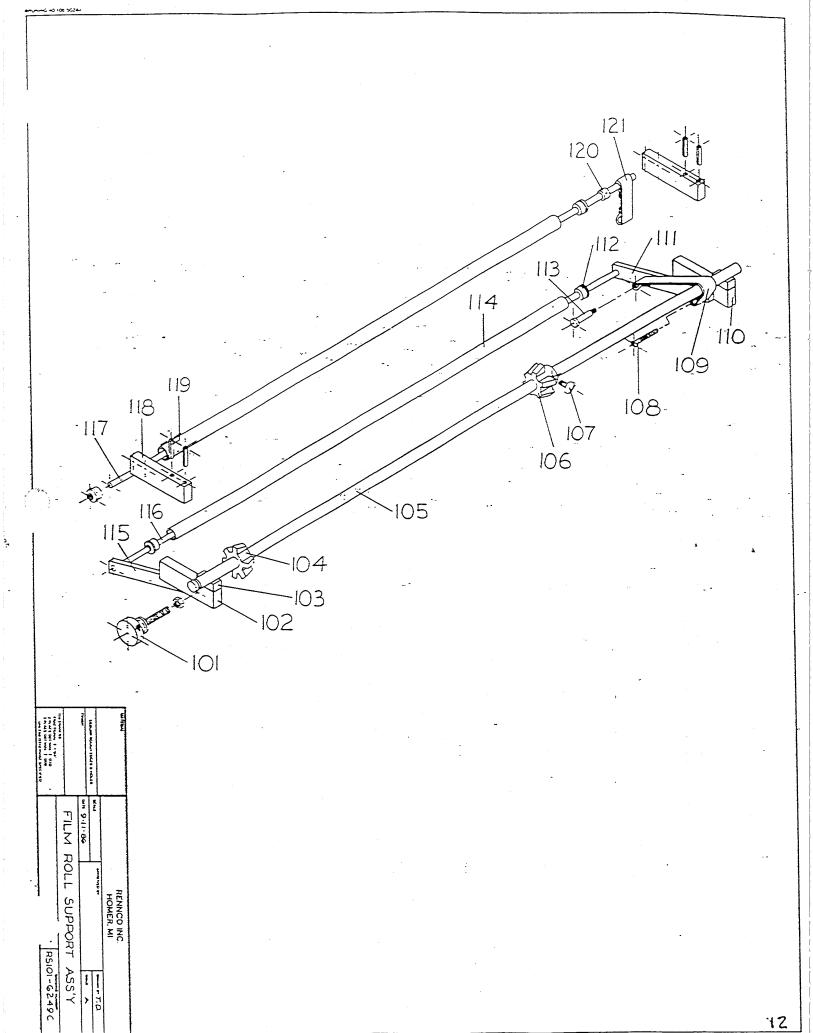
ITEM#	PART#	ISSUE	DESCRIPTION	QTY.
200	R101-450C	E	FILM FEED GUARD .	1
201	R101-448A	Α	ADJUSTMENT ROD	1
202	R101-015A	B	ADJUSTMENT WHEEL SUPPORT	***
203	R101-017A	D	ADJUSTMENT WHEEL	-1
204	3/4-16		JAM NUT	2
205	R101-436A	B	CYLINDER MOUNT BLOCK	2
206	5-DP-7		HUMPHREY CYLINDER	1.
207	MOT USED			
208	R101-105A	Α	SPROCKET MOUNT	1
209	R101-447A	A	WEAR STRIP	1
210	R101-258A	A	CHAIN CLAMP	1
211	R401-092A	A	CYLINDER STOP	1
212	R101-571A	А	FILM FEED BRAKE	1
213	R101-985B	Α	PROXIMITY SWITCH MOUNT	. 7
214	E2E-X5E1		OMRON PROXIMITY SWITCH	1
215	R101-058A P2	B	DRIVE SPROCKET	1
216	RCB121616		TORRINGTON CLUTCH	1
217	#25		ROLLER CHAIN	26 1/2"
218	R101-058A P1	В	IDLER SPROCKET	1
219	B1010		TORRINGTON BEARING	1
220	SHSS23		VLIER SHOULDER BOLT	1



FILM FEED ROLL & HOLD DOWN - 101

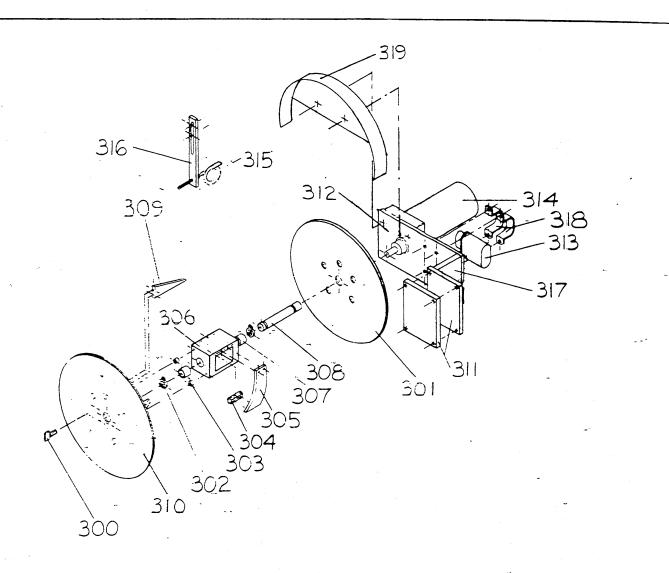
ITEM#	PART#	ISSUE	DESCRIPTION	QTY.
151 152	FB110x3/4 NOT USED		MASTEN BEARING	2
153 *	R101-768A Pi	A	SPACERS	4
154 ×	PB-250-90V-3/	4	90VDC-WARNER BRAKE	1
1,55	R101-607A	E	FILM FEED ROLL SHAFT	i
156	R101-587B	Α	FILM FEED ROLL ASSEMBLY	1
157	R101-709A	Ā	FILM HOLD DOWN SHAFT	1
158	1016D		BOSTON NYLON BEARING	2
159	RS101-2193B	E	21 1/2" FILM HOLD DOWN ROLLER	1
160	MS-17		REID SHOULDER BOLT.	2
161	R101-605A	А	FILM HOLD DOWN BAR	1
162	MS-13		REID SHOULDER BOLT	2
163	8-68		TORRINGTON NEEDLE BEARING	2
164	R101-708B	A	FILM HOLD DOWN BRACKET	2
165	R101-603A	А	TOP FRAME SUPPORT	1
166	3/4"I.D.		SHAFT COLLAR	3

*OPTIONAL ITEMS



FILM ROLL SUPPORT ASSEMBLY - 101

ITEM#	PART#	ISSUE	DESCRIPTION	QTY.
101	R101-572A	A	ADJUSTMENT KNOB	-1-r-1
102	R101-428A P1	B	FILM ROLL SUPPORT BRACKET LOWER FRONT	1
103	R101-429A	Α	FILM ROLL SUPPORT	2
104	R101-467B	B	STATIONARY FILM ARBOR	1
105	R101-606A	C	FILM ROLL SUPPORT SHAFT	1
106	R101-466B	В	ADJUSTABLE FILM ARBOR	1
107	3/8-16 X 1"		THUMB SCREW	1
108	5/16-18 X 3"		ROUND HEAD SCREW	1
109	R101-321A	D	BRAKE STRAP	-I
110	R101-428A P2	B	FILM ROLL SUPPORT BRACKET	
			LOWER REAR	1 1
111	Rì01-048A P1	F	DANCER BAR BRACKET - REAR	1
112	1016D		BOSTON NYLON BEARING	4
113	48519		ALLEN SHOULDER BOLT	1 .
114	R101-599A	В	DANCER & B-WIND TUBE	2
115	R101-048A P2	F	DANCER BARB BRACKET - FRONT	1
116	R101-600A	A	DANCER BAR SHAFT	1
117	R101-601A	A	B-WIND SHAFT	i
118	NOT USED			
119	NOT USED			
120	1/2"I.D.		SHAFT COLLAR	1
121	NOT USED			Ţ

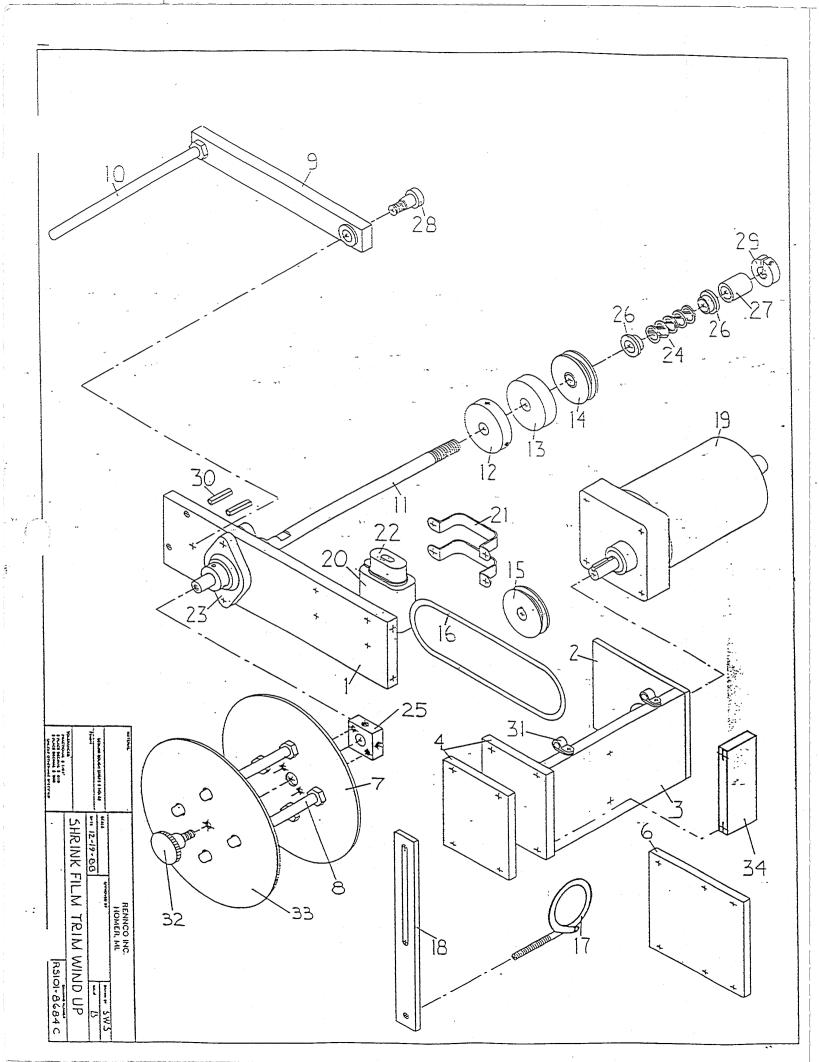


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101 AND 201 RSIOI-6257C	TRIM WIND-UP	ин 9-16-86 A	1 Thronies Louising Co.	HOMER, MI	RENNCO INC

TRIM WIND-UP - 101

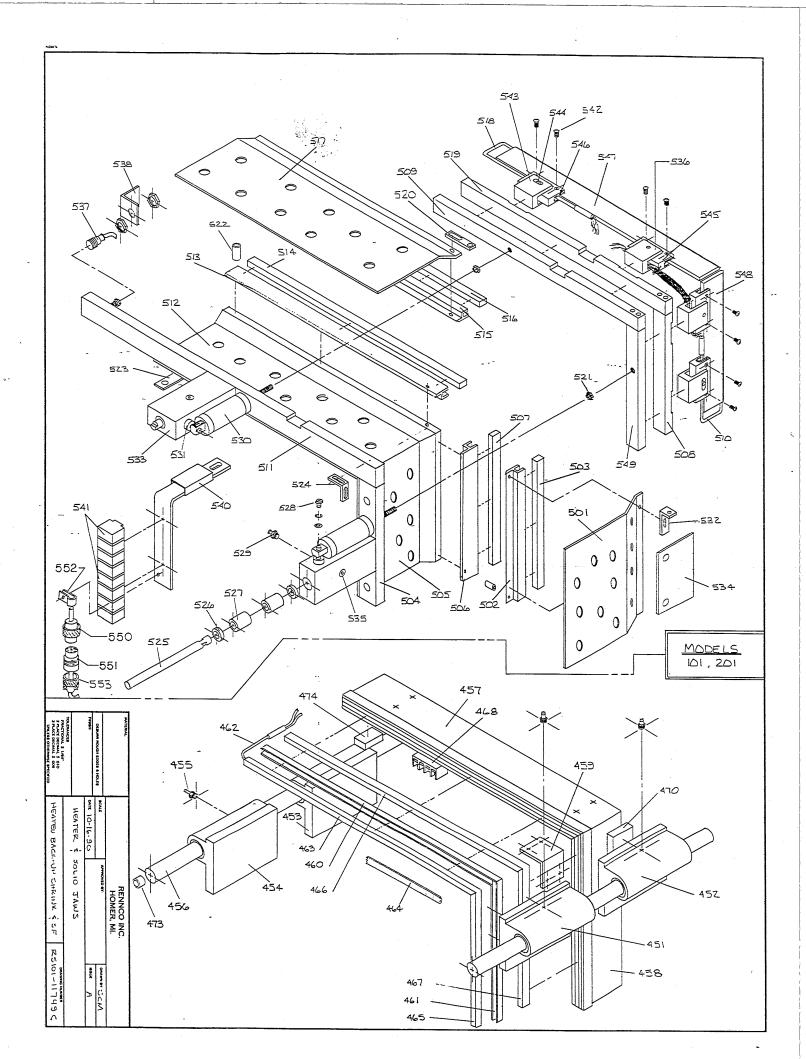
ITEM#	PART#	ISSUE	DESCRIPTION	QTY.
300	5/16-18 X 1/2		THUMB SCREW W/COLLAR	
301	R101-126B	Ε	INSIDE SPOOL	1
302	5100-75		TRUARC RETAINING RING	1.
303	71-1-618-13		KNURLED INSERT	2
304	R101-246A	Ã	STRAP ADJUSTMENT BAR	1
305	R101-245A	Ā	STRAP	<u>.</u>
306	R101-244B	A	CLUTCH BLOCK	1
307	P77-6		BUNTING BRONZE BUSHING	2
308	R101-166A	В	SHAFT	<u>.</u>
309	R101-210A	C	FINGERS	5
310	RS101-129B	G	OUTSIDE SPOOL	1
311	R201-107A	C	SPACER PLATE	2
312	R101-035B	Kalanda	MOUNTING PLATE	1
313	3X685		DAYTON CAPACITOR	1.
314	4Z613		DAYTON GEARMOTOR	<u>1</u>
315	RS101-9563B	A	TRIM GUIDE EYE	1
316	R101-506B	B	TRIM GUIDE EYE BRACKET	1
317	R101-807A	A	MOUNT SPACER	1.
318	3 X 684		DAYTON CAPACITOR CLAMP	2
319	RS101-4583C	A L	TRIM WIND-UP COWL	1

USE PART # R101-170D WHEN ORDERING AN ENTIRE TRIM WIND-UP UNIT, ASSEMBLED. ALL ITEMS ABOVE ARE INCLUDED EXCEPT ITEMS 315 AND 316.



SHRINK FILM TRIM WIND-UP

ITEM#	PART#	SSUE	DESCRIPTION	QTY.
4	RS101-6674B	А	BEARING PLATE	1
2	RS101-6675B	A	MOTOR PLATE	1
3	RS101-6676B	A	SUPPORT BRACE	1
4	R201-107A	С	SPACING PLATE	2
		(8	201,401&501 PKGR. USES ONLY 1)	
6	RS101-6950B	Α	MOUNT PLATE (201 PKGR.)	1
7	R\$101-6677B	В	SPOOL PLATE (INSIDE)	1
8	RS101-7563A	Ā	SPOOL FINGER	4
9	RS101-6679B	A	DANCER BRACKET	1
<u>~</u>	a to their also the also their said to all also	→ .	(101, 401 & 501 PKGR.)	
9	RS101-6948B	A	DANCER BRACKET (201 PKGR.)	1
10	RS101-7564A	A	DANCER FINGER	ī
11	RS101-7567B	A	SPOOL SHAFT	1
12		n A	CLUTCH BACK-UP	1
±с 13	RS101-6682A RS101-6683A	н А _	FELT CLUTCH	1
			CLUTCH PULLEY ASS'Y. W/BRG.	1. 1
14	RS101-8268A	ng A		4
15	RS101-6685A	A	MOTOR PULLEY (BOSTON PULLEY	1.
المام المنظمية المنظ المنظمية المنظمية ا		tama a sa	#PVL2)	.:
16	SCH34-023A	B	RUBBER BELT	1
17	RS101-9563B	A	TRIM GUIDE EYE (101 & 201 PKGR	
17	R401-217B	A	TRIM GUIDE EYE (401 & 501 PKGR	
18	R101-506B	B	TRIM GUIDE EYE BRACKET	1
			(101,201,401 PKGR.)	
18	R5-141B	A	TRIM GUIDE EYE BRACKET	1
	. 		(501 PKGR.)	
19	4Z613		DAYTON GEARMOTOR	1.
20	6X653		DAYTON CAPACITOR	1
21	3X684		DAYTON CLAMP	2
22	3X685		DAYTON TERMINAL BOOT	1
23	FB110-1/2		HUB CITY FLANGE BEARING	2
24	LC-085K-1		LEE COMPRESSON SPRING	1
25	RS101-7566A	Α	INSIDE SPOOL PLATE HUB	1.
26	FL50-3		BUNTING BRONZE FLANGE BEARING	2
27	50-8		BUNTING BRONZE BEARING	j.
28	MS-18		REID SHOULDER BOLT	1
29	CL8-13F		RULAND THREADED SHAFT COLLAR	1.
			(1/2-13)	
30	1/4"DIA.X1"LG.		SPRING PIN	2
31	8912		SMITH CABLE CLAMP (1/4"DIA.)	2
32	DK-19		REID PLASTIC KNOB	1
33	RS101-7565B	A	SPOOL PLATE (OUTSIDE)	- 1
34	R401-221A	A	TRIM WIND-UP SPACER	1 .
			(401 & 501 PKGR.)	



MODEL 101 HEATED BACK-UP SHRINK & SF

T T I WILL	en en en en sa	, - ,		
ITEM# 501		SSUE		TY.
JVI	R8101-11150C	A	8" OUTSIDE VERT. JAW PLATE	1.
2000 JA, JAN,	RS101-11131C	A	14" OUTSIDE VERT. JAW PLATE	1.
502	RS101-8238BP1	A	8" OUTSIDE VERT. GRIPPER EXTRU.	1.
	RS101-8471B P1	Α	14" OUTSIDE VERT. GRIPPER EXTRU.	1
503	R101-431A	Α	8" O.S. VERT. RUBBER GRUPPER	10
	R101-431A	A	14" O.S. VERT. RUBBER GRUPPER	16
504	RS101-8186B	Α	8" VERTICAL JAW FRAME	1
	RS101-11123B	Α	14" VERTICAL JAW FRAME	1
505	RS101-11149C	Α	8" INSIDE VERT. JAW PLATE	1
	RS101-11130C	A	14" INSIDE VERTICAL JAW PLATE	1
506	RS101-8238BP2	 А	8" INSIDE VERT. GRIPPER EXTRU.	1
	RS101-8471B P2	A	14" INSIDE VERT. GRIPPER EXTRU.	1
507	R101-431A	A		
wwr	R101-431A	A	The state of the s	10
508	· · · · · · · · · · · · · · · · · · ·		14" RUBBER GRIPPER MATERIAL	16
JVO	R101-11146A	A	8" VERTICAL HEATER FRAME	1.
a	R9101-11127B	A	14" VERTICAL HEATER FRAME	1
509	RS101-11124B	A	HORIZ. HEATER FRAME MT.	1
510	R101-1015BP3	A	8" VERTICAL HEATER	1
	R101-1015B P6	Α	14" VERTICAL HEATER	1
511	RS101-8744B	C	HORIZONTAL JAW FRAME	1
512	RS101-11129D	А	BOTTOM HORIZ. JAW PLATE	1
513	RS101-11643B P2	A	BOTTOM HORIZ. GRIPPER EXTRU.	1
514	R101-431A	Α	RUBBER GRIPPER MATERIAL	20
515	RS101-11643BP1	Α	TOP HORIZONTAL GRIPPER EXTRU.	1
516	R101-431A	Α	RUBBER GRIPPER MATERIAL	21
517	RS101-11128D	A	TOP HORIZ. JAW PLATE	1
518	R101-1015B PA	A	HORIZONTAL HEATER	1
519	RS101-11125B	A	HORIZONTAL HEATER FRAME	
520	RS101-11540A	n A		1.
~ h. W	MULVETLUTVI	H	RETAINER CUP -	,
521	W /42 O A		TOP HORIZONTAL JAW PLATE	1
	5/16-24		JAM NUT	2
522	7022F		SMITH HEX STAND-OFF	2
523	RS101-8187A	Ä	L.H.BTM.HORIZ. JAW PLATE SPACER	1.
524	RS101-11369A	A	CORNER CLIP-JAW PLATE RETAINER	1
525	R101-732A	B	GUIDE SHAFT	2
526	NOT USED			
527	NOT USED			
528	10-32X3/8		PAN HEAD MACHINE SCREW	2
529	HGF-13		REID GREASE FITTING	2
530	5DP1		HUMPHREY CYLINDER	2
531	NOT USED			
532	RS101-11541A	A	ANGLE CLIP - JAW PLATE RETAINER	1
533	R101-1124B	A	BEARING BLOCK ASS'Y	2
534	RS101-8188A	A	L.H. OUTSIDE VERTICAL -	!
		171	JAW PLATE SPACER	•
535	91256A535		GREASE HOLE PLUG	1
536	R101-1125A	Α		2
537	E2E-X5E1	m	STATIONARY HEATER MOUNT ASS'Y	2
538		_	OMRON PROXIMITY SWITCH	1
	R101-1126A	A	FLOATING HEATER MOUNT ASS'Y	2
539	R101-1069A	A	FRONT PROXIMITY SWITCH ACTUATOR	1
540	RS101-12302B	Α	ELEC. HEATER BOX BRK'T.	1.
541 = 43	110SP		MARATHON TERMINAL BLOCK	j.
542 5 / 5	NOT USED			
543	NOT USED			
544	NOT USED			
545	NOT USED			

MODEL 101 HEATED BACK-UP SHRINK & SF

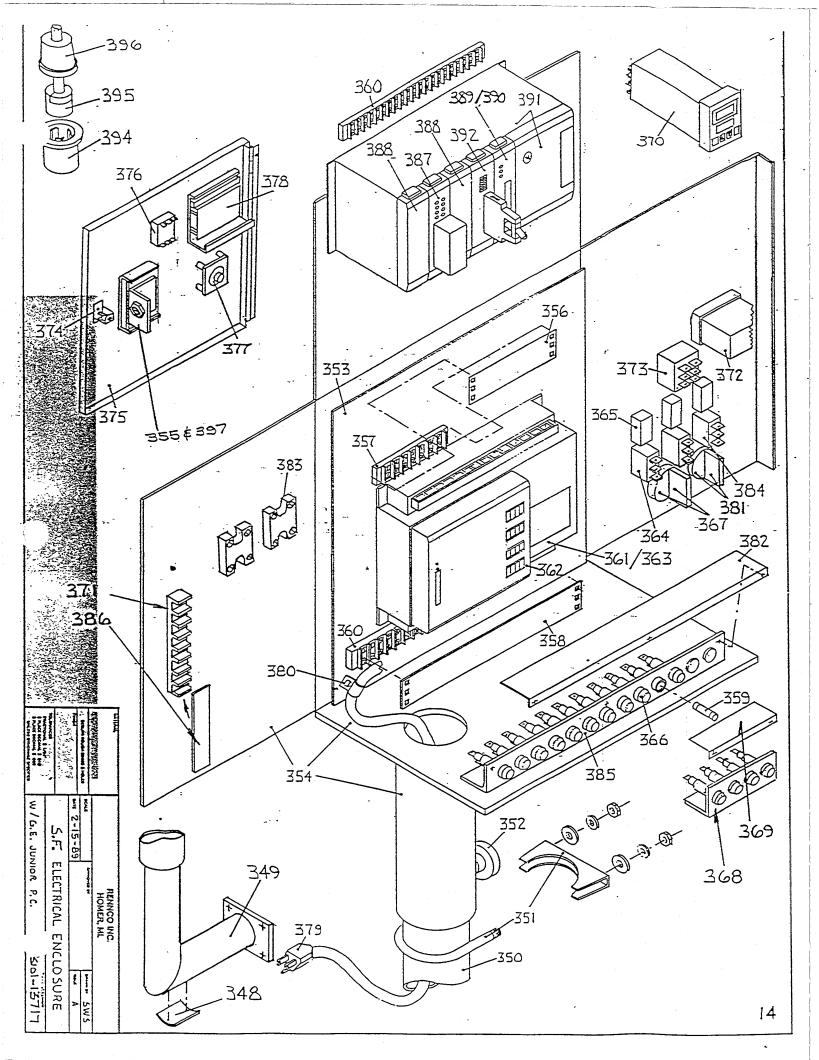
ITEM#	PART#	T (" (" 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	77, 370 ,27, 17, 17, 17, 17, 17, 17, 17, 17, 17, 1	
TIELL	rmr i m	ISSUE	DESCRIPTION	QTY.
546	RS101-10423A	A	TEFLON SPACER	4
547	* SEE NOTE		20" HORIZ. SEALER BLADE	1
548	* SEE NOTE		8" VERTICAL SEALER BLADE	1
	* SEE NOTE		14" VERTICAL SEALER BLADE	1
549	RS101-11145B	A	8" VERTICAL HEATER FRAME MOUNT	1
	RS101-11126B	A	14" VERT. HEATER FRAME MOUNT	1
550	5000110-10		JOY (4PIN) MALE RECEPTACLE	2
551	5000110-4		JOY (4PIN) FEMALE PLUG W/A'COR	
552	31F2282		AMEROCK GROWMET	. <u>-</u> 1
553	R101-1095B	A	ELEC. BOX, HEATER CONN.	1
554	R101-1071A	A	FRONT PROX. SW. ACTUATOR SPACE	
555	R5-052A	Α	PROXMITY SWITCH MOUNT	1

^{*} FOR REPLACEMENT SEAL BLADE PART NUMBERS, GET NUMBER DIRECTLY OFF THE BLADE ITSELF.

SF

SOLID JAW PARTS & SUPPORT BLOCK 101 W/HEATED BACK-UP SHRINK & SF

ITEM#	PART#	ISSUE	DESCRIPTION	RTY.
450				
451	RS101-11121A	A	L.H. FRONT JAW SUPPORT BLOCK	1
452	R101-913A	A	R.H. FRONT JAW SUPPORT BLOCK	1.
453	R101-912A	Α	R.H. REAR JAW SUPPORT BLOCK	1
454	R101-914A	A	L.H. REAR JAW SUPPORT BLOCK	1.
455	HGF-13		REID GREASE FITTING	4
456	R101-585A	A	CLAMPING SHAFT	2
457	RS101-11116B	A	HORIZONTAL SOLID JAW	1
458	RS101-11137B	A	8" VERTICAL SOLID JAW	1
	RS101-11118B	A	14" VERTICAL SOLID JAW	1
459	R101-1020B	A	SOLID JAW CORNER BRACKET	1.
460	RS101-11119B	A	HORIZ. H-CHANNEL	1
461	RS101-11140B	Ã	8" VERT. H-CHANNEL	1.
	RS101-11056B	Α	14" VERT. H-CHANNEL	1.
462	R101-1122B	A	8" VERT. HEATER, SILICOME BACK-UP	1
	R101-1052B	A	14" VERT. HEATER, SILICONE BACK-UP) 1
463	RS101-11120A	A	HEATED SILICONE - HORIZONTAL	1
464	T-10X18 YD. R	OLL	PARFLEX TEFLON TAPE -1/4"X10 MIL	2
465	RS101-11142A	A	8" VERT. HEATED SILICOME	1.
	RS101-11058A	A	14" VERT.HEATED SILICONE	4
466	RS101-8967A	A	SILICONE FOAM CUSHION - HORIZ.	1
467	RS101-8853A	A	8" VERT. SILICONE FOAM CUSHION	1
	RS101-8956A	A	14" VERT.SILICONE FOAM CUSHION	1
468	MK6-4		KLIPPON TERMINAL BLOCK	1.
469				
470	RS101-8190A	A	VERT. JAW SPACER - FRONT	1
471			•	
472				
473	RS101-1825A	B	CLAMPING SHAFT SPACER	2
474	RS101-8189A	A	HORIZ. SOLID JAW SPACER – REAR	1



SF

ELECTRICAL ENCLOSURE PARTS - 101 SMOKE FREE

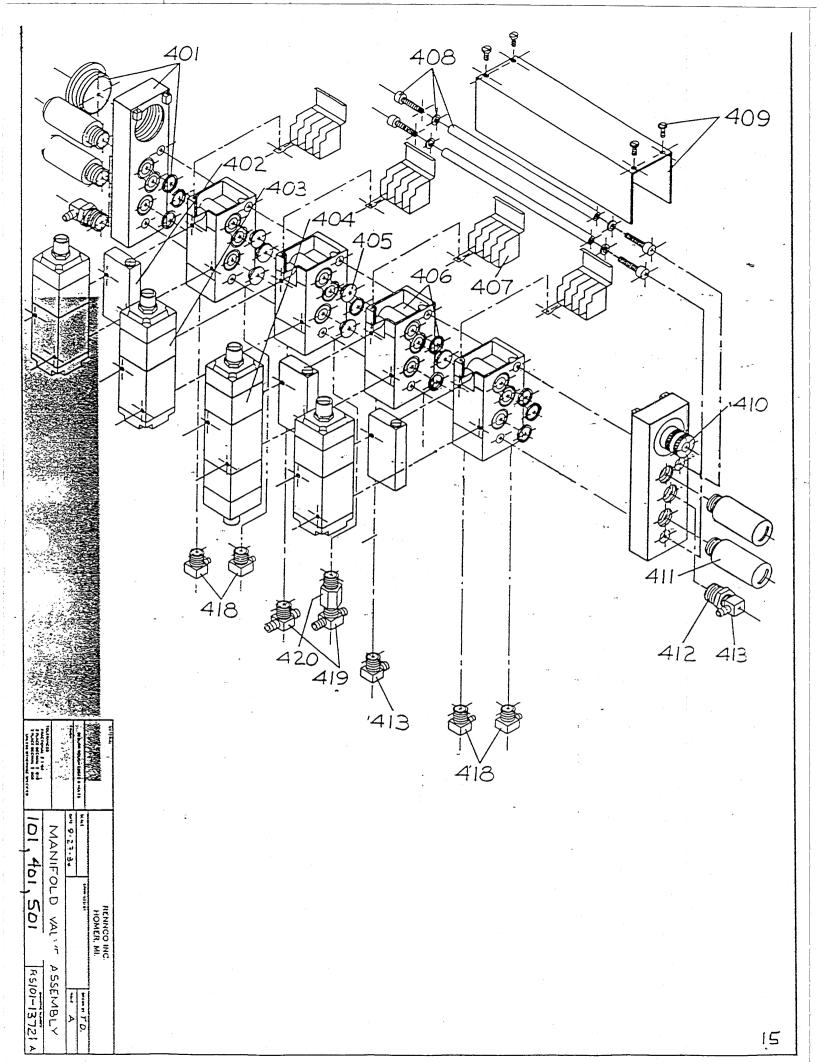
ITEM#	PART#	ISSUE	DESCRIPTION	QTY.
350 351	R101-752B 3/8-16	B	ENC. SUPT. TUBE 2 1/2" I.D. MUFFLER CLAMP	
352	DK-19		REID KNOB	1
353	R101-987C	A	ENC. SUB PANEL	1
354	R101-1064B	A	MACHINE ENCLOSURE	1
355 356	S300-8AC	A	BACK-UP HEATER CONTROL	1
357	CW110 110SP		MARATHON TERM BLK COVER	1.
358	1105F CW124		MARATHON TERMINAL BLOCK	1
359	ABC-15		MARATHON TERMINAL BLK COVER	1.
<i>007</i>	ABC-5		FUSE - 15 AMP	1.
	ABC-3		FUSE - 5 AMP FUSE - 3 AMP	1
	AGC-1		ruse - 3 MMP FUSE - 1 AMP	1.
360	124SP		MARATHON TERMINAL BLK	10
361	10609SJR102		GE JR. BASIC PC.	1
362	IC609TCU100		GE TIMER/COUNTER SET POINT UNIT	
363	IC610ACC151		GE PROM MEMORY CHIP	1
364	160011E653		ARROW HART NON LIGHTED	4.
1			SPST SWITCH	2
365	1609DUM11		ARROW HART FILLER PLUG	2
366	HKPHH		LITTLEFUSE FUSEHOLDER	13
367	PW3P23		MICRO-SWITCH PUSHBUTTON - RED	1
1	PW3CD		MICRO-SWITCH N.O. CONTACT BLOCK	(1
368	MOT USED			
369				
370	965-1CD0-00	00	WATLOW HEATER CONTROL	2
371				
372	P2-4906-115	AC.	REDDINGTON COUNTER	1
373	2600HR11E		ARROW HART LIGHTED DPST SWITCH	1
374	44-99-116-1	1	SOUTHCO KNOB LATCH	1
	44-99-222-5	·1.	SOUTHCO KEYED LATCH OPT	
375	RS101-13002	CA	MACHINE ENCLOSURE DOOR	1
376	088221		INFITEC ONE SHOT MODULE OPI	
377	P1800-24		I MEGA OHM POT. OPI	1

ELECTRICAL ENCLOSURE PARTS - 101 SMOKE FREE PAGE 2

ITEM#	PART#	ISSUE	DESCRIPTION	QTY.
378 379 380 381	CBC-700-90 15143SJ 115 NOT USED		WARNER BRAKE CONTROL OPT. AMERICAN POWER CORD SET JIFFY CLIP	the terms the
382 383 384	R101-990B SSRT-240D25 1600HR11E	A	FUSEHOLDER COVER P&B SOLID STATE RELAY ARROWHART LIGHTED SPST SWITCH	- 17 mm
385 394 395 396	R101-989B NOT USED NOT USED NOT USED	Α	FUSEHOLDER MTG. BRKT	-
397	R101-1117A	Α	MTG. TRACK, BACK-UP HTR. CONTROL	. 1.

USE THE FOLLOWING ITEMS WHEN THE STANDARD SERIES ONE IS USED IN PLACE OF THE SERIES ONE JUNIOR.

358	CW124	MARATHON TERM BLOCK COVER (ADTL)	-1
360	124SP	MARATHON TERMINAL BLOCK (ADTL)	1
		MANATURA TERMINAL BEACK (ADIE)	.i.
362	1C609TCU100A	GE TIMER/COUNTER SET	1.
387	IC610MDL175A	GE SERIES ONE OUTPUT MOD	1
388	IC610MDL100A	GE SERIES ONE FILLER MOD	1.
389	IC610CPU104A	GE SERIES ONE CPU MOD	1
390	IC610ACC155A	GE PROM MEMORY CHIP	1
391	IC610CHS110A	GE SERIES ONE CHASSIS	1.
392	IC610MDL106A	GE SERIES ONE INPUT MOD	1
393	IC610CBL105A	GE SERIES ONE INTERFACE CABLE	1



MANIFOLD VALVE ASSEMBLY PARTS

57

ITEM#	PART#	DESCRIPTION		
401	ME401LR	SMC RIGHT & LEFT END PLATES W/O-RINGS	1	
402	SP0100	SMC INTERFACE SPEED CONTROL W/GASKET	3	
403	NVS4114-0009D	SMC SINGLE SOLENOID VALVE (SPR RET)	4	
404	NVS4214-0009D	SMC DOUBLE SOLENOID VALVE	1	
405	AXT336-6	SMC GALLERY BLOCKING DISCS	6	
406	MB4010-02	SMC MANIFOLD BLOCK WITH O-RINGS	5	
407	AXT336-21A	SMC TERMINAL BLOCK	5	
408	AXT336-5-5	SMC 5 STATION TIE-RODS WITH SCREWS	2	
409	MXT336-4-5	SMC 5 STATION CONDUIT COVER WITH SCREWS	1	

PART HUMBERS SHOWN FOR TIMES 408 AND 409 ARE FOR STANDARD 5 STATION VALVE ASSEMBLY. IF OTHER THAN 5 STATION, CHANGE LAST DIGIT OF PART NUMBER TO INDICATE THE NUMBER OF VALVE STATIONS.

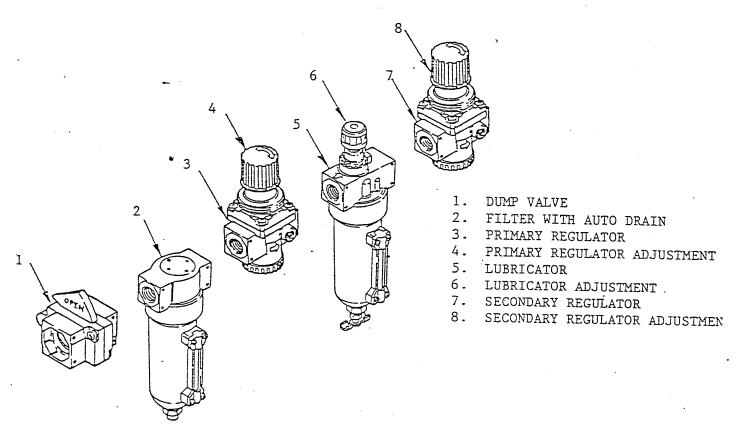
410	DB3	PYLE/NATIONAL CORD GRIP 1	
411	3/8 N.T.	WAIRCOM BREATHER 4	
412	209P-6-4	REDUCER BUSHING 2	
413	229-6-4	MALE ELBOW 4	
414	216P-4-2	REDUCER NIPPLE 1	
415	F10BK	FLOW CONTROL VALVE 1	
41.6	231-4-2	RUN TEE	
417.	218P-4	HEX HEAD PLUG , 1	
418	229-4-4	MALE ELBOW 4	
419	232-6-4	BRANCH TEE 2	
420	222P-4-4	ADAPTER 1_	_

UNIT B REQUIREMENTS PRIOR TO START-UP

SECTION 1 SUPPLY AIR SYSTEM OPERATION, ADJUSTMENT, CONSUMPTION

1.1 FRL UNIT OPERATION (FILTER-REGULATOR-LUBRICATOR UNIT) A dump valve is provided ahead of the FRL Unit as a means of stopping and starting the main air supply to the machine. When the dump valve is pushed upward, it starts the air flow through the FRL Unit. When pushed downward, all the air that is trapped in valves and cylinders is exhausted to the atmosphere.

The filter unit is intended to remove solids down to 5 microns. It is not intended as a water and oil removal filter. It will remove water to a certain degree, but if the shop air coming to the machine is excessively wet, it will not remove enough water for trouble-free operation. In this case, an air dryer or moisture separator should be used in the air system, or a coelescing water-oil removal filter added at the packager. CAUTION: Dirty, moisture laden air can damage the valving system.



1.2 <u>LUBRICATOR</u> <u>ADJUSTMENT</u> The lubricator is factory set, and can be checked for proper operation by noting the number of drops of oil that fall from the stem as viewed through the sight dome on top of the lubricator. One drop should fall for every 7-8 cycles of the packager.

If readjustment is necessary, turn the recessed screw adjustment to the sight dome counter clockwise to decrease flow. When necessary, refill oil bowl with #6 velocite oil or #10 non detergent air lubricant.

CAUTION: Over-oiling the valve system will eventually lead to malfunctioning of the spools in the valves.

UNIT B REQUIREMENTS PRIOR TO START-UP

SECTION 1 SUPPLY AIR SYSTEM OPERATION, ADJUSTMENT, CONSUMPTION

1.3 <u>REGULAR ADJUSTMENT</u> Models 101, 201, and 401 have a main and secondary regulator. 101 and 201 main regulator is normally set at 80 PSI and secondary regulator at 40 PSI. Model 401 main regulator is normally set at 40 PSI and the secondary at 20 PSI.

Models 501-36 and 501 have 3 regulators, a main and 2 secondary. The main regulator is set at 100 PSI and controls the film feed function, seal cooler air blast and jaw opening function. The first secondary regulator is set normally at 60 PSI and controls the heater cylinders. The other secondary regulator is normally set at 20 PSI and controls the pressure of the main drive cylinder when the jaws are closing.

In some cases, the prescribed settings may be different than those indicated above. Check the labels mounted on the regulator gauges and refer to the air circuit drawing.

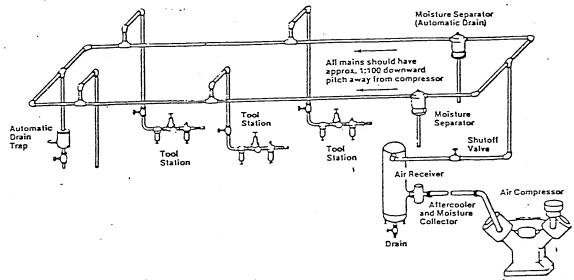
Regulator adjustment is made by loosening the lock nut or ring and turning the adjustment knob clockwise to increase pressure, counter clockwise to decrease pressure.

Because the filter has an automatic drain feature and will dump accumulated water when it reaches a certain level, make sure no electrical components or power cord connectors are located under or near the filter.

PAGE 18
UNIT B REQUIREMENTS PRIOR TO START-UP

SECTION 1 SUPPLY AIR SYSTEM OPERATION, ADJUSTMENT, CONSUMPTION

1.4 RECOMMENDED AIR PIPING SYSTEM DIAGRAM



1.5 AIR CONSUMPTION The air consumption for your system as shipped is shown on the specifications page UNIT A, SECTION 2.1. The following list of air operated optional equipment and their air consumption is provided in the event they are added to the original equipment at a later date. The air consumption is given per cycle because all systems operate at different cycle rates. To find the consumption of these options if applied to your system, multiply the figure given by the cycles per minute that your system operates.

	CUBIC FEET
BASIC PACKAGERS	PER MACHINE CYCLE
Model 101	
Model 201	
Model 401	
Model 501 AND 501-36	
Model 101 with large jaw opening	
Model 401 with large jaw opening	.18
OPTIONAL EQUIPMENT	
Bucket Conveyor with 4" wide buckets	.06
Bucket Conveyor with 8" wide buckets	
Pusher Infeed (average types - 12" stroke) .	
Hot Hole Punch	
Cold Hole Punch	
SCH-34 Hot Roll Leaf Imprinter	
RC-1000 Electronic Counter	
Seal Cooler	
Product Shelf	02
Pocket Conveyor	.12
CCL Cup Counter/Loader	.10

EXAMPLE: Model 201 with Pusher Infeed, Cold Hole Punch and SCH-34 Imprinter .10 + .09 + .004 + .035 = .229 Cubic Feet per machine cycle. If packager is to cycle 20 times per minute: .220 x 20 = 4.58 Cubic Feet per minute (SCFM).

UNIT B REQUIREMENTS PRIOR TO START-UP

SECTION 2 ELECTRICAL REQUIREMENTS

2.1 ELECTRICAL REQUIREMENTS An 8 foot power cord with grounded plug is provided. Connect to properly grounded circuit of correct voltage and amperage ratings. WARNING: Bypassing or severing the ground lug on the cord plug may result in personal injury. Electrical specifications for your system as shipped are shown on the specifications page UNIT A, SECTION 2.1. The following list of optional equipment and their electrical ratings is intended as a guide in the event they are added at a later date.

MODEL 201 8 X 10 = 6 AMPS @ 120 VOLTS A.C. MODEL 101 14 X 20 = 8 AMPS @ 120 VOLTS A.C. MODEL 401 14 X 36 = 7 AMPS @ 240 VOLTS A.C. MODEL 501 14 X 42 = 7 1/2 AMPS @ 240 VOLTS A.C. MODEL 501 14 X 52 = 7 AMPS @ 240 VOLTS A.C.

OPTIONAL EQUIPMENT	AMPS @ 120 VOLTS A.C.
Discharge Conveyor 12" Wide	3.8
Discharge Conveyor 24" Wide	4.0
Hot Hole Punch	
SCH-34 Imprinter	
Electric Eye for Film Registration .	
Static Eliminator	.5
Vacuum Trim Removal	10.0
RC-1000 Electronic Counter	
RC-1000 with Hopper	3.5
Infeed Conveyor	1.5
Pocket Conveyor	1.5
CCL Cup Counter/Loader	2.0

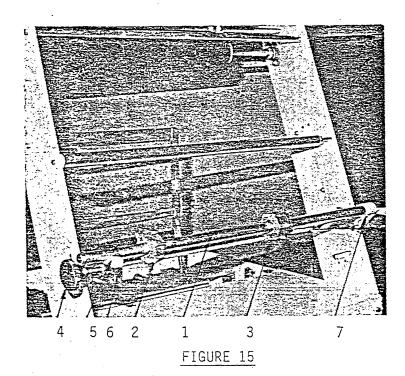
NOTE: Amperages shown for heaters are maximum. Actual average working amperage is somewhat less.

SECTION 1 POWER UP AND TEMPERATURE ADJUSTMENT

- 1.1 POWER-UP Turn on air supply to packager.
 - Move the main electrical power switch to the "on" position. This switch provides power to the sealing elements and the exhaust blower. The switch labeled "trim" provides power to the trim wind-up motor.
- 1.2 <u>TEMPERATURE ADJUSTMENT</u> Temperature control adjustment depends on many factors. The temperature controls are factory set at time of shipment and should give satisfactory initial operation. Refer to temperature control adjustment in UNIT D, SECTION 5.1 AND SECTIONS 6.1 AND 6.2.

SECTION 2 LOADING FILM

2.1 <u>LOADING FILM</u> (<u>NOTE</u>: Remember that the load side of the machine is the front and that the control panel side is the left side of the machine. The position of individual components will be referred to by the same relationship).



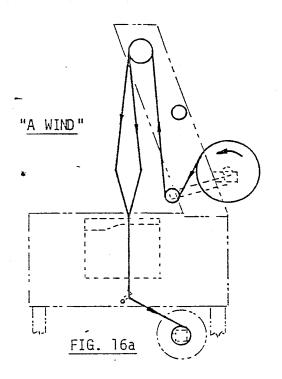
- 1. Film Roll Shaft
- 2. Front Film Roll Arbor
- 3. Rear Film Roll Arbor
- 4. Adjustment Knob
- 5. Film Roll Nylon Support (Roller Bearings on Model 501)
- 6. Film Roll Support Mount Block
- 7. Brake Strap

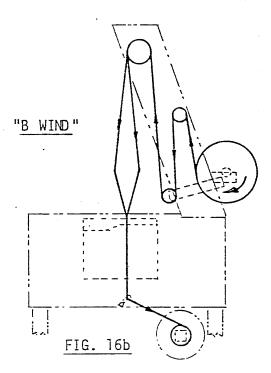
Loosen one end of the brake strap to lift off the film roll shaft from its supports. Remove the rear arbor (with thumb screw). Put film roll onto shaft with open end of film toward front arbor. Replace rear arbor into film roll core and be sure arbors are gripping core tightly. Tighten thumb screw. Place shaft on supports and replace brake strap.

<u>UNIT</u> <u>C</u> INITIAL SET-UP PROCEDURES

SECTION 3 FILM THREADING DIAGRAMS & PROCEDURES

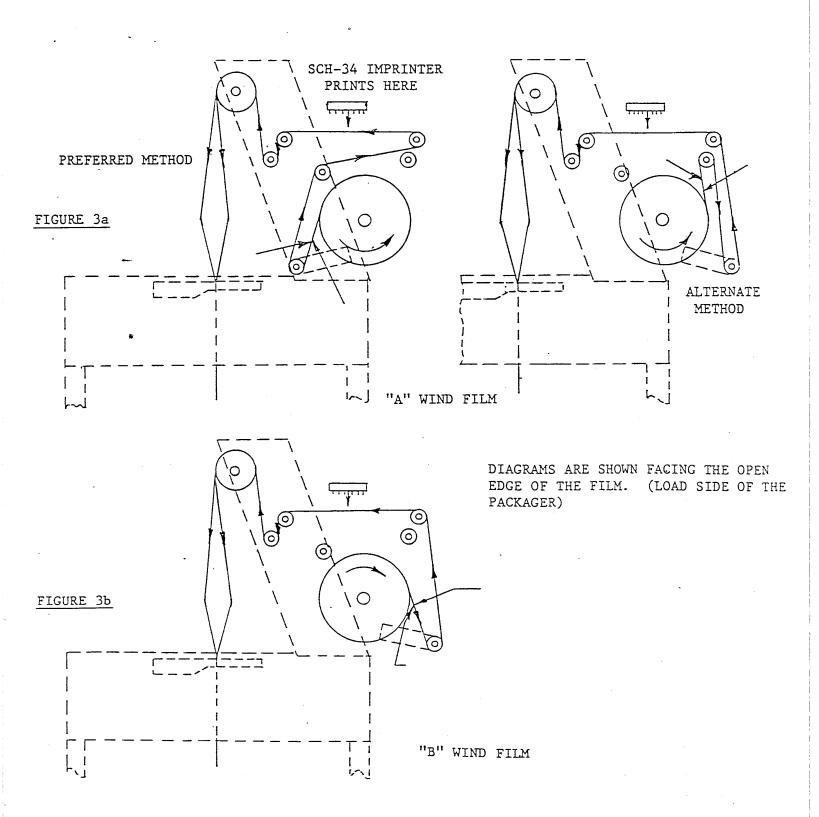
3.1 FILM THREADING DIAGRAMS Figures 16a and 16b show the threading method for a standard machine. For film threading of SCH-34 Imprinter mounted to packager see the following page. On some applications the threading may be different than shown because of special attachments. In any case, attachments should not interfere with the tracking of the film. They should not push or distort the film from its otherwise straight travel between one guide roll to the next.





SECTION 3 FILM THREADING DIAGRAMS

FILM THREADING DIAGRAMS FOR PACKAGER WITH SCH-34 IMPRINTER



SECTION 3 FILM THREADING DIAGRAMS & PROCEDURES

3.2 MAKING THE FIRST BAG After threading the film over the film feed roll, place it around the film guide bar, chute, or pusher infeed, depending on how your machine is equipped. Depress the jaw lock open/safety reset push button momentarily to open the jaws. Advance the film manually so it is below the jaws 6-8 inches. Lower the film hold down; assembly into position.

<u>WARNING</u>: The following procedure requires placing hands near moving machine parts! Be sure hands and fingers are visible at all times. A second person <u>should not</u> be used to operate the jaws while another is advancing the bag and tying the trim tail.

NOTE: The above description is for operation of a Model 101 or 201. For operation of Model 401 and 501 equipped with safety door, see Unit D, Section 7.3.

REFER TO SECTION 4 AND CHECK OPERATION OF JAW SAFETY AT THIS TIME.

See Figures 18a and 18b - Grasp the lower outside corner of the film below the jaws, and pull downward and outward. Hold the jaw lock open/safety reset button for one full second and then release to close the jaws and make the seal. Tap the jaw lock open/safety reset button to open the jaws. The film will advance. Do this enough times to create a trim tail that will reach the trim wind-up spool. Route the trim tail through the trim guide eyebolt with the trim wind-up switch off and the spool stopped, tie off the trim tail to one of the 5 spool fingers. Turn trim wind-up switch on and close the jaws.

At this time, the packager is ready to be loaded with product and operated. Refer to UNIT D for details of specific machine functions and for adjustments needed in changeover.



FIGURE 18A

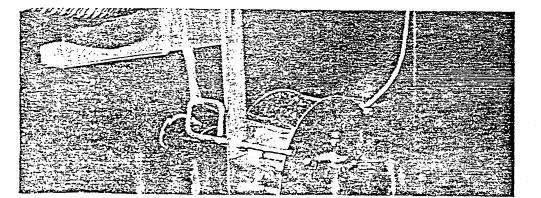


FIGURE 18B

SECTION 4 JAW SAFETY ADJUSTMENT

4.1 THE PURPOSE of the jaw safety system is to open the jaws if something other than film is caught between the jaws when they are closing.

<u>WARNING:</u> Personal injury can result if safety is not adjusted properly and hands or fingers are caught between the moving jaws.

CAUTION:

**Safety adjustment should be checked daily or before each shift

**Never assume safety is operating properly without checking it first
**Never place hands between jaws even if safety is adjusted and working
properly

NOTE:

**The safety is designed to actuate on anything 3/16" thick or larger. Items less than 3/16" thick may not actuate safety

**If the speeds of the jaws opening and closing are changed, the safety must be readjusted.

There are two safety system adjustments to set which work in conjunction with each other. Refer to UNIT A, SECTION 3.7 for locations.

- 4.2 ADJUSTMENT OF THE ACTUATOR SCREW that actuates the jaws closed proximity switch should be made as follows: With the jaws closed and the air pressure turned on, loosen the jam nut on the actuator screw and turn it so that it moves away from the switch. The led on the switch will go out. Then turn the screw toward the switch until the led turns on again. At that point continue to turn the screw 1/4-1/2 turn more.
 - * NOTE: Cycle the packager and test to see if the setting is as sensitive as it can be. Readjust if necessary.

 NOTE: Some packagers with longer jaw assemblies are equipped with 2 jaw closed proximity switches located at each end of the horizontal jaw. For safe operation of the machine, both switch actuator bolt adjustments must be made correctly.
 - 4.3 THE SAFETY TIMING is set by decreasing the number on the safety thumbwheel timer so that the packager will not complete its cycle when operating. NOTE: Use only R.H. thumbwheel to adjust the safety. The three L.H. thumbwheels must remain set at "0" for this timer to work properly. Now with the jaws locked open, increase the safety timing by 1 and attempt to close the jaws by depressing the safety reset button. Repeat until jaws stay closed and the heaters advance. Once this happens, leave the setting where it is.

NOTE: Changing the main drive cylinder closing speed will necessitate repeating the timing adjustment. Also, if the jaws will not stay closed and advance the heaters, the screw adjustment may need to be repeated.

Check for proper operation of the jaw safety system by purposely closing the jaws on an object such as a small rubber hose approximately 3/8"-1/2" diameter. If the safety is adjusted correctly, the jaws will open promptly when they close on the object.

WARNING: DO NOT PUT HANDS IN JAWS.

SECTION 5 HEATER DWELL ADJUSTMENT

- 5.1 <u>PURPOSE OF HEATER DWELL</u> It provides an adjustable timing to regulate how long the heater stays plunged into the film.
 - The operation of the heater dwell is as follows: The dwell timing begins at the same time that the heaters are signaled to advance, so the dwell time includes both the amount of time that it takes the heaters to advance to the film, <u>plus</u> the time that they stay extended to make the seal.
- 5.2 <u>ADJUSTMENT</u> OF THE HEATER DWELL TIMER is done by setting the two R.H. thumbwheels to an approximate initial setting of 20. It will then be necessary to increase or decrease the setting to get the best seal with the particular film being used. Generally, the thicker the film is, the higher the setting will have to be.

SECTION 1 SHRINK TRIM WIND UP ASSEMBLY MACHINES WITH SHRINK TYPE SEAL ASSEMBLY

1.1 SHRINK TRIM WIND UP OPERATION Most shrink films require a more sensitive trim wind up unit due to their inherent tear properties. Because of this, the trim wind up unit is provided with a friction disc clutch that allows a more infinite adjustment. The friction disc is usually felt and in normal use will not require attention. However, in time, the felt will wear or become filled with contaminants. If adjustment of the tension provides jerky operation, or if a lack of tension is the problem, the felt disc may need to be replaced. In doing so, clean the mating surfaces of the adjacent metal discs.

TRIM TENSION ADJUSTMENT (Refer to exploded parts page 15) Trim tension should be kept at a maximum that will not break the trim tail. Also, it should be pointed out that the recommended trim tail width is 1 inch, and the machine may not function properly if less than this amount is provided. Adjustment is made by loosening the clamp screw of the threaded clamp collar, Item #29, and turning the collar clockwise to add tension or counter clockwise to lessen the tension while holding the spool, Item #8, from turning.

The tension should be such that the trim is pulled immediately when the film starts to advance. If the spool hesitates at the time the film advances, the trim tail will go slack for an instant, then when the spool does begin to turn, it may take up the trim abruptly and cause it to break. Another important factor is the routing of the film through the trim guide eye bolt, Item #17. If the trim tail is pulled too hard sideways rather than downward, it may cause the film to tear in the corner where the vertical and horizontal seals meet. It is best to arrange the position of the eye bolt so the trim tail is pulled downward as much as possible.

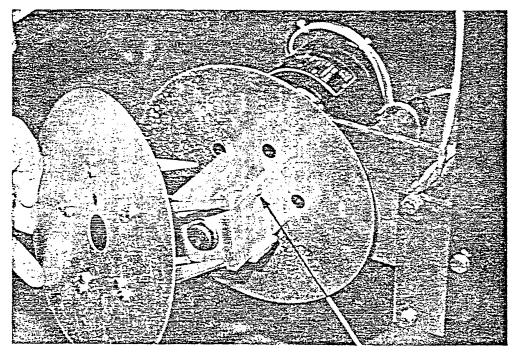
SECTION 1
STANDARD TRIM WIND UP ASSEMBLY MACHINES EQUIPPED WITH TYPE "SF" SEAL ASSEMBLY

1.2 <u>STANDARD TRIM WIND UP TENSION ADJUSTMENT</u> - Trim tension should be kept at a maximum that will not break the trim tail.

*It should be pointed out that the recommended minimum trim tail width is 1 inch. If the trim is less than 1 inch, the trim wind up assembly may not be able to be set with enough tension to aid film advancing and tracking.

*Trim tension is accomplished by a leather strap that acts as a slip clutch to transfer power from a continuous run gearmotor to the wind up spool. Tension can be adjusted by turning the adjustment screw shown in Figure 19. Turn the screw clockwise to increase tension, counterclockwise to decrease.

Trim tension should be adjusted so that as the film advances the trim tail is kept taught during the entire time the film advances.



TENSION ADJUSTMENT SCREW

SECTION 2 FILM GUIDANCE AND TRACKING

- 2.1 <u>FILM GUIDANCE AND TRACKING</u> One of the main factors that contribute to the performance of the packager is how well the film guides nad spreaders form the opening that accepts the product. Your packager is equipped with guides and spreaders to do this job effectively, but there are a few things to check if problems arise.
 - A. Symmetrical Film Spreading Looking from the front (load side) of the machine, any attachments above the jaws (film guide, spreader bars or plates, chutes, or infeed mechanism) should be centered on a line from the film feed roll to the jaws in the closed position. These attachments, if not centered, will cause more pressure against one of the film webs than the other. This will make the two edges of the film webs get out of alignment with each other and create unnecessary wrinkles and distort the shape of the bag. See Figure 20.

Looking from the left side (control panel) of the machine, there are several considerations.

B. Film Roll Position The center fold edge of the film roll and where the edge passes over guide rollers, film feed roll and finally along the edge of the film guide bar should all line up. Lay a straight edge along the end surface of the film roll (preferably as large a roll as possible). The centerfold edges of the film where it passes over the guide rollers and the edge of the film guide should line up with the straight edge. See Figure 21a. This should be done with the film guide adjusted squarely to the jaws.

If the film roll is too far toward the front of the machine, the film will bunch up on the film guide. See Figure 21b.

If the film roll is too far toward the rear of the machine, the centerfold edge of the film will move away from the film guide bar and the trim tail will become narrow and either be cut off or broken. See Figure 21c.

Adjustment of the film roll position can be made with the film adjustment knob. See UNIT C, SECTION 2, Figure 15.

After adjusting the film roll as above, it may be found that even though the film edges are lined up properly, the film bunches up at the top corner of the film guide bar similar to Figure 22a. In this case, it is caused by how far the film is being spread open. To solve this problem, tilt the film guide as shown in Figure 22b. Note that the bottom tip of the film guide is held at a point that keeps the film edge in line just the same as if the film guide were adjusted square to the jaws. In otherwords, while the bottom tip of the film guide is kept in alignment with the film roll edge. The top of the film guide is tilted in.

SECTION 2 FILM GUIDANCE AND TRACKING

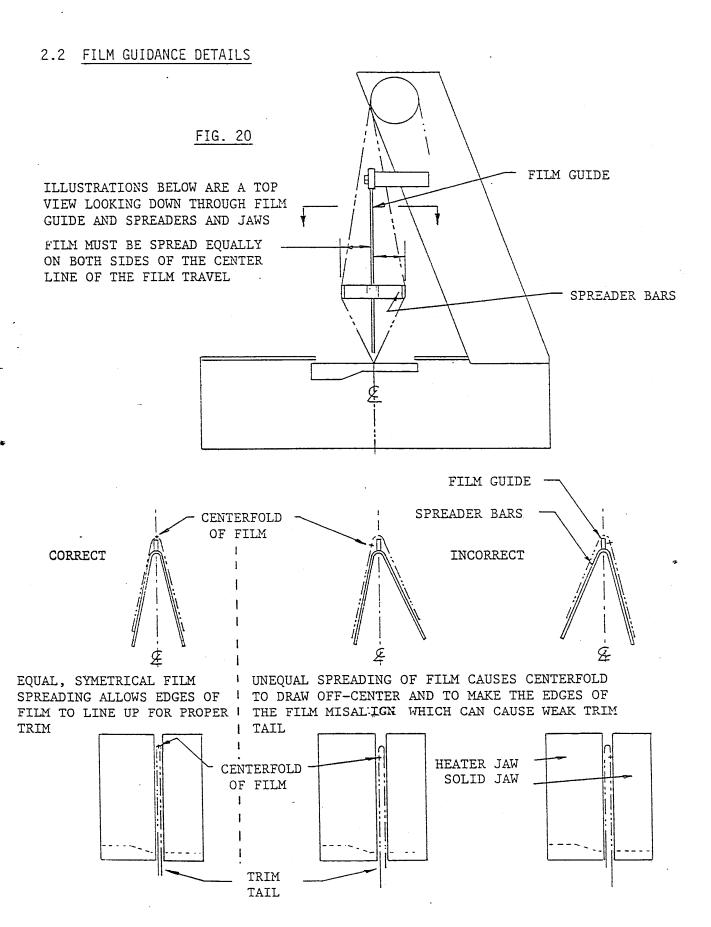
2.1 FILM GUIDANCE AND TRACKING, Continued

Bag Shape Problems Figures 23a and 24a show bag shapes that can C) occur for several reasons. In most cases, these problems are caused by bulky products and by spreading the film quite side because of In any event, the wider the film is spread, the more that it is pushed sideways away from the vertical jaw. This pushing or sideways movement of the film usually happens when the jaws open to release the film and before the trim wind-up can take up the slack in Trim wind-up tension is important because of this. It is good practice to have enough tension on the trim so that it pulls the film immediately as soon as the jaws open and the film starts to feed. Bulky products with tight bag sizes add to the problem, especially on single pack type jaws. In this case, after the film has advanced, the jaws have to close around the product and in doing so have to squeeze the two film webs together. This tends to push the film sideways away from the vertical jaw. This creates the effect as shown in Figure 23a where the corner of the previously made bag is drawn sideways out of alignment with the vertical heater creating a triangular tab at the bottom corner of each bag. This can usually be corrected as shown in Figure 23b by moving the trim guide eye bolt up and away from the vertical jaw to create a more sideways pull on the trim tail. Adding tension to the trim wind-up helps

Figures 24a and 24c show a similar situation; however, because these are pouch pack jaws, the effect is different. Normally because the vertical bag dimension is shorter than the vertical heater, the vertical heater passes through and wipes the already-made seal of the previous cycle. If the already-made seal is not in alignment with the vertical heater when it advances, a notch is made in each bag. Figure 24a shows what can happen if the pull on the trim tail is too hard sideways. This can be corrected by moving the trim guide eye bolt toward the vertical jaw slightly, allowing the corner of the already-made bag to track straight downward in line with the vertical heater, as shown in 24b.

Figure 24c shows what can happen with bulky product, wide film spreading and too little trim tension. The top corner of the already made seal is allowed to move away from the vertical heater as it advances down. This can be helped by pulling the trim more sideways as shown in Figure 24d. This in turn will pull the top corner of the seal into alignment with the heater, adding trim wind-up tension if necessary.

SECTION 2 FILM GUIDANCE AND TRACKING



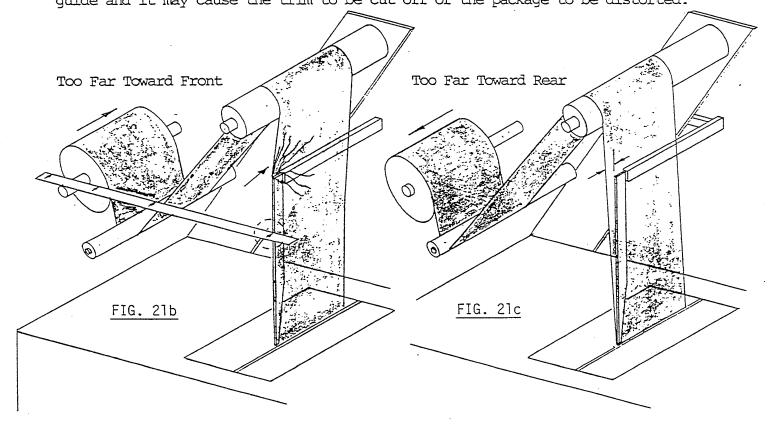
SECTION 2 FILM GUIDANCE AND TRACKING

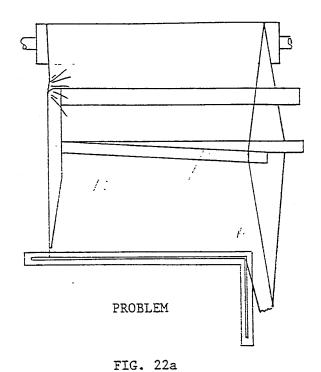
2.2 FILM GUIDANCE DETAILS

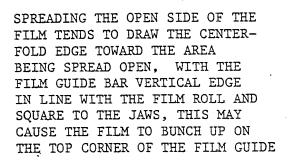
With the film roll properly positioned the centerfold edge of the film will contact a straight edge at points shown indicating the edges are alligned.

With the film guide in the same position as above, if the film roll is positioned too far toward the front of the machine the film will bunch up at the corner of the film guide. If the film roll is too far away from the front of the machine, the film will not contact the film guide and it may cause the trim to be cut off or the package to be distorted.

FIG. 27a







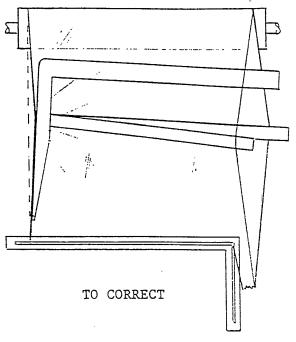


FIG. 22b

KEEPING THE BOTTOM TIP OF THE FILM GUIDE IN LINE WITH THE FILM ROLL (DOTTED LINE) WHILE TIPPING THE TOP CORNER AWAY FROM THE CENTERFOLD, ALLOWS THE CENTERFOLD EDGE TO TAKE ITS NATURAL DRAW TOWARD WHERE THE FILM IS BEING SPREAD OPEN. THIS ALLOWS THE FILM TO TRAVEL OVER THE FILM GUIDE MORE SMOOTHLY.

SECTION 2 FILM GUIDANCE AND TRACKING

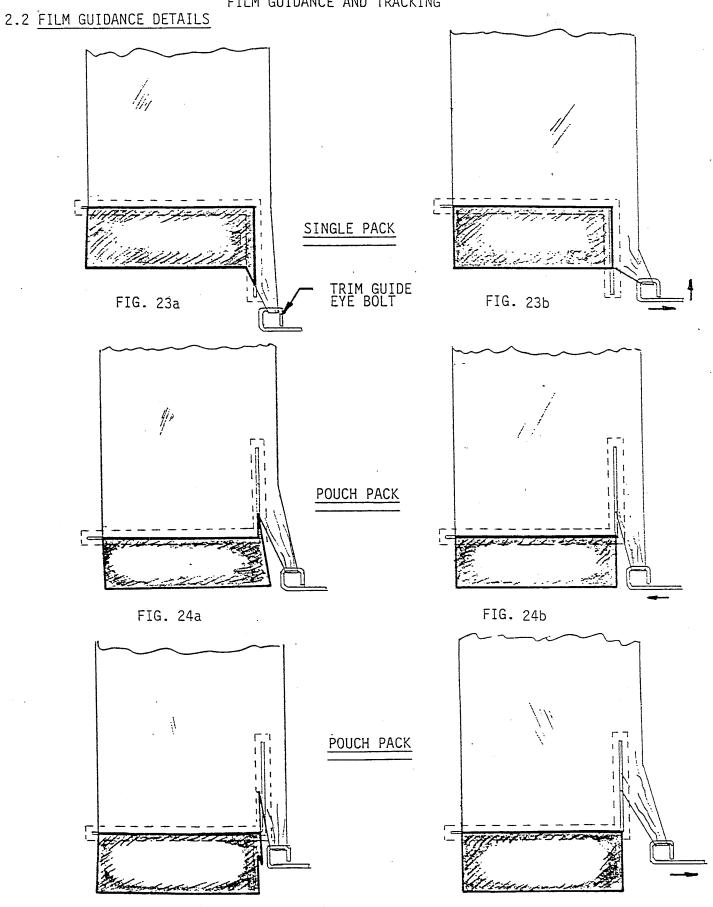


FIG. 24c

FIG. 24d

SECTION 3 FILM FEED AND FILM HOLD DOWN

3.1 <u>FILM FEED FUNCITONS</u> The film feed drive mechanism is composed of a cylinder driving a chain that turns the film feed roll through a one-way clutch on the shaft. The stroke of the cylinder can be adjusted to produce bags of different vertical dimensions.

The adjustment can be made by loosening the lock screw and turning the adjustment wheel as indicated by the label to either increse or decrease the film travel. Refer to Figure 25.

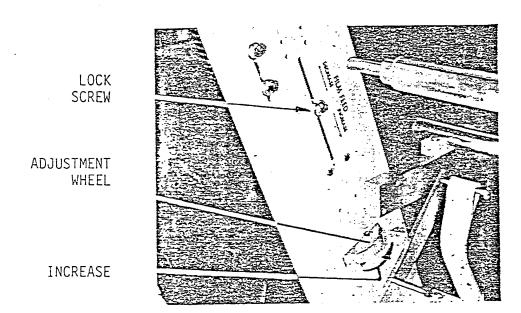


FIGURE 25

The film feed drive mechanism contains some additional features that should be noted. Refer to UNIT A, SECTION 3.3.

As the cylinder extends, the film is being fed. As the cylinder reaches the end of its stroke, two things happen: 1) The cylinder block contacts the nylon pinch brake which grips the film feed shaft to limit over-travel. Because of this, the nylon brake should be kept clean and free of oil. 2) The cylinder block also actuates the film advanced proximity switch. This switch must be actuated before jaws can close.

IMPORTANT: It is necessary that the cylinder block does not bottom out on the switch but rather bottoms out on the nylon brake.

If packager is equipped with optional electric eye, the electric brake must be the component that stops the film feed roll. In this case the cylinder must retract prior to contacting the pinch brake.

SECTION 3 FILM FEED AND FILM HOLD DOWN

- 3.2 <u>FILM FEED DRIVE ROLL</u> The film feed drive roll is responsible for pulling the film from the film roll. Slippage of the film on the film feed drive roll is of primary importance as it can result in an inconsistent vertical bag dimension. Several causes of slippage are:
 - 1) Dirty film feed drive roll use denatured alcohol to clean the feed roll often. It should be kept clean of dirt and oil and the slippery talc coating that sometimes accompanies packaging films.
 - 2) Dirty film roll supports the nylon film roll supports should be kept clean as they serve as a bearing surface to allow the film roll to spin more easily when the film is pulled off. If dirty, they can create enough drag to make the dancer bar ineffective in its job of pulling the film from the roll.
 - 3) Film slip properties films are rated according to their slip properties. It is important to use low to medium slip films on the Rennco Packagers.
- 3.3 DANCER BAR ASSEMBLY The purpose of the dancer bar is to: 1) Provide a web loop or an excess length of film so that the film feed drive roll does not pull film directly from the film roll but rather from the excess loop by lifting the dancer bar which requires less force. 2) The dancer bar also actuates the brake strap so that when the film stops advancing, the dancer bar settles back to its low position which applies the braking action necessary to keep the film roll from over traveling and which keeps the film legs taught. Loose, dropping film webs can contribute to poor film tracking over the guide rollers and film feed drive roll.
- 3.4 <u>FILM HOLD DOWN ASSEMBLY</u> The loose jointed film hold down assembly serves to create equal pressure along the full width of the film on the film feed drive roll. It should be kept clean in the same fashion as the film feed drive roll.

SECTION 4 JAW DRIVE COMPONENTS

4.1 <u>MAIN DRIVE CYLINDER</u> The main drive cylinder operates a pivoting transfer shaft assembly that transmits the open and close motion to the jaw assemblies through linkage arms. See UNIT A, SECTION 3.2.

The cylinder is equipped with adjustable air cushion valves that help reduce the noise and wear caused by the jaws reaching the open position. It should be noted that these cushion adjustments are effective for only about the last 1/2" of cylinder travel in each direction and have nothing to do with controlling cylinder speeds.

They cylinder rod is fastened to the tapped hole in the drive clevis and can be adjusted in or out to get small changes in the amount of jaw opening. It is factory adjusted and should not require adjustment, but if necessary, the rod can be screwed further out of the clevis to create slightly more jaw opening.

IMPORTANT: If the rod is screwed too far out of the clevis, it may be possible to detract from the gripping pressure when the jaws are in the closed position.

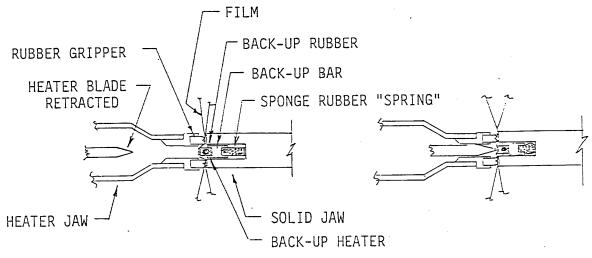
4.2 TRANSFER SHAFT ASSEMBLY The transfer shaft pivots in bronze bushings, which should not require regular lubrication. The linkage arms contain needle bearings, which should be lubricated according to the maintenance schedule in UNIT G.

SECTION 5 JAW ASSEMBLY - SHRINK FILM AND TYPE "SF"

5.1 <u>SEALING METHOD</u> (Refer to Figure Fig. 26) All films require that the two film webs be held flat and always in contact with each other at the time that the seal bar advances to make the seal. This is accomplished by the fact that the rubber back up protrudes out from the gripping surfaces of the solid jaw. The purpose is not to stretch the film over the back up rubber, but to simply keep the webs of film from separating.

To create the seal, a heated blade with a special edge configuration is used to provide enough pressure to melt and press the two webs of film together, and at the same time separate the sealed bag from the rest of the film. A bead is created at the edge of the film while a small area adjacent to the bead is sealed flat. The strongest seal is created when the film is not under tension but is relaxed. The rubber back-up provides a means of relaxing the flim slightly at the time the blade contacts it. The edge of the back-up rubber opposite the sealing edge is made of foam rubber which compresses as the blade pushes against it. This "springing" effect allows the film to relax and follow the blade as it moves forward.

The solid back-up rubber contains a heating element that raises the temperature of the rubber to approximately 150 degrees F (66 degrees C). The heated back-up rubber allows the seal to be made with a blade temperature somewhat lower than would be possible without a heated back-up. Lower blade temperatures help keep molten film (especially polyethylene) from building up on the blades.



Film is gripped against solid jaw surfaces. Back-up bar sponge is relaxed.

Heater blade extends, pressing film into back-up rubber, compressing sponge rubber, relaxing film; creating the seal.

SECTION 5

JAW ASSEMBLY - SHRINK FILM AND TYPE "SF"

5.1 SEALING METHOD, Continued

Approximate temperature ranges for shrink films are 400 - 450 F (205 - 233 C). For polyethylene films the range is 330 - 400 F (166 - 205 C). These are approximate ranges that can be used at initial start up of most films of average thickness and sealing characteristics. Each specific type of film must be run to determine the optimum temperature setting.

SECTION 5 JAW ASSEMBLY

Refer to UNIT A, SECTION 3 for component identification and UNIT G for scheduled maintenance and lubrication.

5.2 GRIPPING AND JAW ALIGNMENT Gripping and jaw alignment on type "SF" and shrink jaws is a matter of making sure the jaw plates and heater blade are assembled to a certain dimensional relationship, then adjusting the back-up jaw assembly to the heater jaws. Disconnect air supply. The heater jaw should be checked first by removing the horizontal top jaw plate and the inside vertical jaw plate. Check the heater blade alignment by measuring from the inside surface of the jaw frame to the tip of the heater blade in the extended condition. The dimension should be 5". This dimension must be checked at both ends of the horizontal blade and the vertical blade and the blades must touch and align in the corner where they meet. This can be adjusted by screwing the cylinders in or out. If binding occurs, it may be necessary to loosen the guide shaft blocks.

The jaw plates are to be checked next using a dimension of 4 7/8" from the leading edge of the gripper to the inside edge of the jaw frame. This makes it so the blade protrudes past the rubber grippers 1/8" when the blade is extended

In order to adjust the position of the outside vertical jaw plate, if required, it will be necessary to loosen the 2 socket head bolts that attach the vertical jaw frame to the jaw support block. Because the outside vertical plate is sandwiched between these parts, this will allow it to move.

Remove the back-up rubber and "H" channel. At this point, close the jaws by hand (not under air pressure) and bring the rubber gripper into contact with the back-up jaw, but don't compress the rubber. The back-up jaw surfaces should be touching the gripper rubber full length. If they are not, the back-up jaw must be brought into alignment with the jaw plates on the heater jaw. Adjust the vertical back-up jaw first, if necessary, by loosening the two bolts that fasten the vertical back-up jaw to the angle corner bracket. Then loosen the 2 socket head bolts that fasten the vertical jaw frame to the jaw support block. Pivot the vertical back-up jaw into alignment and retighten the bolts taking care to keep the corner right where the vertical and horizontal back-up jaws meet. Retighten teh mounting bolts and double check alignment.

Next, check horizontal back-up jaw alignment to the bottom horizontal jaw plate. Bring the back-up jaw into alignment by first loosening the 2 bolts that fasten the horizontal back-up jaw to the angle corner bracket, then loosen the hex bolts that fasten it to the real jaw support block. Retighten bolts after alignment is correct.

Now the top horizontal and inside vertical jaw plates can be assembled in place and adjusted into alignment with the back-up jaw.

SECTION 5 JAW ASSEMBLY

5.2 GRIPPING AND JAW ALIGNMENT, Continued

When properly aligned, the top of the heater blade, when it is extended, is in alignment with the leading edges of the rubber grippers both horizontally and vertically. Also, the gripping surfaces of teh back-up jaw mate to the rubber grippers on the jaw plates in such a way as to provide even, consistent gripping forces over the entire length of the jaw.

To test the grip, hold the hand flat near the jaw plate and press the tips of the fingers into the film horizontally near the rubber grippers. It should be difficult to pull the film from the jaws. Test the grip above and below the horizontal jaw and on the inside andoutside of the vertical. It may be necessary to adjust a jaw plate slightly if it isn't gripping.

IMPORTANT: In all adjustment having to do with alignment of the jaw parts, it is best to loosen and adjust one component at a time then recheck its position before continuing on to adjust other parts. Making several adjustment at one time can lead to worse mis-alignment problems than there were to start with. Feel free to contact the Rennco Service Department for advise before attempting major adjustment.

5.3 JAW CONFIGURATION Figure 27 illustrates the necessary relationships between jaw plate opening, solid jaw groove and heaters.

NOTE:

- 1) The width between the gripper rubbers should be centered on the width of the solid jaw.
- 2) The heater should be aligned with the center of the slot in the solid jaw.

The adjustment necessary to gain the alignment between plates and solid jaw are the bolts that fasten the vertical jaw frame to its jaw support block and the bolts that fasten the vertical solid jaw to its jaw support block. When making an adjustment to align the horizontal jaws to each other vertically, take care not to pivot the vertical jaws from a true vertical position.

SECTION 5 JAW ASSEMBLY

Heater blade must move in and out smoothly Heater blade should be centered on rubber back-up surface. The opening and must not scrape gripper extrusion as it passes through the opening. With jaws between the rubber grippers should be open, and with heaters extended, the tip centered on the solid jaw groove. of the blade is 1/8" beyond the leading edge Back-up bar assembly must slide easily of the rubber in the solid jaw cavity when it is degripper. pressed. 3 18 SOLID JAW -BACK-UP SPONGE HEATER BLADE BACK-UP BAR HEATING ELEMENT BACK-UP RUBBER HEATER CLAMP BACK-UP HEATER HEATER MOUNT HEATER JAW FIG. 27 JAW CONFIGURATION DETAILS

5.4 <u>HEATER ALIGNMENT</u> The alignment of the heater blades to both the opening between the jaw plates that they come out of and the rubber back-up in the solid jaw they go into is critical to the quality and strength of the seals.

Important considerations are

- 1) The heater blade <u>must</u> pass through the opening between the jaw plates without scraping the plates.
- 2) Make sure the "L" shaped heater frame that supports the heater bars moves in and out smoothly and that it is parallel with the jaw frame both vertically and horizontally. In addition, the heater frame must stay parallel to the jaw frame as it moves. That is, one end must not get ahead of the other.
- 3) The heat being used to make the seal causes both the heater blade and heater clamps to expand. The longer the seal length, greater the amount of expansion. If this expansion is not allowed to happen, the blades will become bowed and seal quality will be affected. The "L" shaped heater assembly is mounted with a clevis that is fixed, and a slotted clevis that allows the heater clamp to move. If for some reason the heater clamps are removed, care must be taken when reinstalling them so that the heater clamps can slide inside the slotted clevis.

SECTION 5 JAW ASSEMBLY

5.4 HEATER BLADE ALIGNMENT, Continued

4) As shown in Figure 27, the back-up rubber must move in order to make the best seal. The back-up rubber assembly consists of the solid silicone rubber face piece, a silicone sponge back piece, and a stiffener bar that holds both pieces of rubber. It is the sponge silicone that gives the back-up jaw its spring loading. In order for the spring effect to work, the cavity that contains the back-up bar must be kept free of contaminants that might keep the back-up from moving.

SECTION 5
JAW ASSEMBLY

5.5 HEATER BLADE AND HEATING ELEMENT REPLACEMENT

<u>WARNING</u>: Disconnect electric and air supply. The mechanism in the jaw cavity contains pinch points, so if the air supply is left on for purposes of checking heater alignment, <u>do not</u> place fingers in jaw cavity. Allow the jaws to cool before disassembly.

If only the horizontal sealer assembly is to be serviced, it can be accessed by removing the machine top plate and then the horizontal jaw top plate. Service can be done without removing the entire "L" shaped heater frame assembly.

If the vertical sealer assembly is to be serviced it is generally easier to remove the "L" shaped heater frame assembly from the jaws so it can be worked on at a bench.

CAUTION: The sealer blades are teflon coated. The coating is easily damaged which will cause difficulty in obtaining proper seals. TAKE EXTREME CARE IN HANDLING THE SEAL JAWS TO GUARD AGAINST BLADE DAMAGE.

If the heater frame assembly is to be removed from the machine, disconnect the heater and thermocouple wiring that comes from the packager electrical enclosure and pull the wires through the strain relief grommet (E) at the terminal block.

Label the wires for proper reassembly later. Remove the hex head bolts that join the heater frame mount (7) to the heater frame ass'y (6). Lift the heater frame assembly straight vertically taking care not to scrape the teflon coated blade surfaces.

To remove the blades, loosen the 2 socket head screws in each of the heater clamp assemblies (8). Remove the 2 screws from the clamp closest to the corner only, the screws in the rest of the clamps can be left loose but in place. Slide the blades endways away from the corner where horizontal and vertical meet, then outward away from the clamps. To remove the heating element, slide it out of the blade.

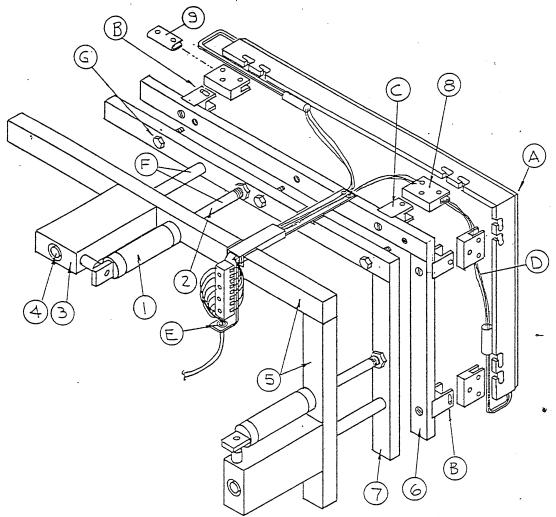
Reverse the procedure to reassemble. Take care to:

- (1) make sure the teflon spacer (9) is in position when installing the screws in the clamp closest to the corner,
- (2) make sure the tip of the heating element does not protrude past the end of the blade where horizontal meets vertical,
- (3) retighten clamp screws,
- (4) route wiring so that it is captivated and cannot be damaged,
- (5) <u>make sure teflon coating is not damaged when replacing the heater</u> <u>frame assembly.</u>
- (6) double check heater wiring to get the thermocouple continuity correct. The red wire is the negative (-) WIRE.
- (7) check heater alignment and make sure blades meet and touch in the corner.

SECTION 5 JAW ASSEMBLY

5.5 HEATER REPLACEMENT

Standard single pack jaws are shown. Pouch pack details are similar.



- Heater blades must touch in the corner. Α.
- Blade clamp must be allowed to slide in the floating heater mount for В. expansion.
- C. Fixed heater mount.
- Route wiring so that it won't be damaged. D.
- Wires going to the electrical enclosure must be gripped by the grommet and E. should be routed so they do not rub on machine parts.
- Do not loosen cylinder or guide shafts to remove the heater frame F. assembly.
- Loosen these bolts to remove heater frame assembly.
 - Heater Cylinders 1.
 - Cylinder Rod 2.
 - 3. Bearing blocks
 - 4. Guide Shaft

- 5. Jaw Frames
 6. Heater Frame Ass'y
 7. Heater Frame Mount

- 8. Blade Clamp 9. Teflon Spacer

SECTION 6 TEMPERATURE CONTROLS

6.1 <u>TEMPERATURE CONTROL OVERVIEW - SEAL JAW</u> Two separate temperature controls provide separate power to the horizontal and vertical heaters. Due to thermal differences in the jaw configuration and the grain structure of packaging films, separate controls are required to get the best results on each seal.

The state-of-the-art micro processor controls chosen for the Rennco Shrink and type "SF" packagers are designed to hold the operating temperature at the seal bar to within a few degrees of the set point value. The control also has features that allow it to be adjusted to suit the thermal characteristics of the Rennco Packager at time of assembly, then engage a "LOC" electronically so only the temperature set point function is available to machine operators. If necessary, the control can be "unlocked" by maintaining personnel in order to change the parameters of operation, then the "LOC" can be engaged again when it is put back into service.

At time of final assembly at Rennco, the controls are set to "Auto Tune" the system, which is described in later pages. The "Auto Tune" function allows the controller to tune its operation parameters to the specific machine it is installed in. Once the "Auto Tune" function is performed, it never needs to be done again until a new temperature control is installed.

The only adjustment that needs to be made is to set the temperature to get the best seal with the film being used. This is done with the "Up/Down" keys. All other keys and their functions are not adjustable unless the "LOC" is removed.

The termocouple is an integral part of the heating element. It senses temperature in approximately the center of the heater. The lead wires are solid wire (not stranded) and must be kept from flexing as they will fatigue and break. Continuity of the thermocouple lead wires is important because if they are connected incorrectly, the temperature controller will not function properly. The red wire is always the negative (-) wire, the white wire is the positive wire. The thermocouple is a "grounded" type junction, which means it has continuity with the heater sheath tubing.

TEMPERATURE CONTROL OVERVIEW - BACK-UP JAW - The back-up heater in the silicone back up rubber serves to warm the back-up rubber to a temperature of 150 deg. F (66 deg.C to 74 deg. C). Warming the back-up rubber helps to make seals at a lower seal blade temperature which helps to reduce poly film build up on the blade. The back-up heater is powered by a control that supplies a fixed voltage. The temperature of the rubber should not need to be adjusted for different applications. However, incoming power line differences from customer to customer may require a slight initial adjustment. See section 6.2.1 for adjustment procedure.

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UNIT D MACHINE FUNCTION DETAILS & ADJUSTMENTS

SECTION 6
TEMPERATURE CONTROLS

CAUTION: OPERATING THE BACK-UP RUBBER AT TEMPERATURES HIGHER THAN INDICATED ABOVE CAN DAMAGE THE BACK-UP JAW COMPONENTS.

SECTION 6 TEMPERATURE CONTROLS

6.2 TEMPERATURE CONTROL OPERATION

SERIES 965 MENUS

Set Up

Used to establish levels of operator access, input type, units of measure, low and high range limits, and output 2 configuration.

Operation

Used to enter the set point and the tuning valves, and alarm set points, parameters for proportional band, reset, rate and cycle time for outputs 1 and 2, alarm low and high, dead band, calibration offset and auto tune.

Calibration

Use of the calibration menu is not required. If the calibration menu is accidentally initiated, press the mode key repeatedly to return to the normal display. The controller is in this menu when "CAL" appears in the upper display.

The values for the parameters of the above menus were entered at the factory when the machines were auto tuned. The information provided on the following pages is provided for an understanding of how the controls function and to provide information on troubleshooting the heating system.

It is suggested that if the values that are preset into the control at the factory are inadvertently altered, the values on the following pages be entered in and the control be "Auto Tuned" again. This will bring it back to its original operation.

DO NOT PUT THE CONTROLLER IN THE MANUAL MODE WHILE "CAL" IS DISPLAYED. THIS WILL CAUSE THE CONTROL TO CHANGE ITS CALIBRATION AND WILL RESULT IN HAVING TO BE RECALIBRATED AT THE FACTORY.

TEMPERATURE CONTROLS

6.2 TEMPERATURE CONTROL OPERATION, CON'T

How to Use the Keys and Displays

Use this page to learn the nature and function of the Series 965's keys and displays.

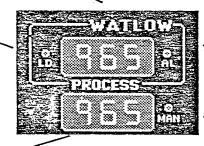
Series 965 Keys, Displays and Load LED's

Upper Display

Red, 0.3" (8 mm) high, seven segment, three digit LED display, indicating either process actual temperature, the operating parameter values, or an open sensor. When powering up, the Process display will be blank for 5 seconds.

L D

When lit, this LED tells you when the control output is energized.



AL

When lit, this LED tells you when the alarm is active.

Lower Display

Red 0.3" (8 mm) high, seven segment, three digit LED display, indicating the set point, output value, prompts for data in the upper display, or error and alarm codes.

MAN

Lit when the control is in Manual operation. Press the A/M key twice to enter Auto operation. When blinking, this indicates that pressing the A/M key will toggle between Auto and Manual. After 5 seconds without pressing the A/M key, the LED stops blinking, and returns to its previous state.

UP/DOWN Keys

When pressed simultaneously for 3 seconds, the Setup Menu appears displaying the LOC parameter. Continue to press the UP/DOWN keys, and the Calibration Menu appears.

MODE Key

Steps the control through the Operating menu; also, in the Auto mode, new data is self entering in 5 seconds.



AUTO/MAN Key

Pressed once, it clears any latched alarms. If pressed again within 5 seconds, the control toggles between Auto and Manual mode. While in Manual mode, percent power is in the lower display.

UP Kev

Increases the value of the displayed parameter. A light touch increases the value by one. Holding the key down increases the value at a rapid rate. New data is self entering in 5 seconds.

DOWN Key

Decreases the value of the displayed parameter. A light touch decreases the value by one. Holding the key down decreases the displayed value at a rapid rate. New data is self entering in 5 seconds.

SECTION 6
TEMPERATURE CONTROLS

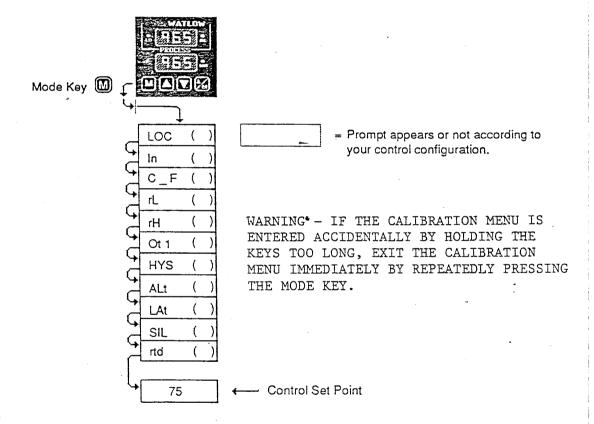
How To Setup The Series 965

Setting up the Series 965 is a simple process. First configure the 965's features to your application in the Setup Menu, then enter values in the Operating Menu. Both tasks use the MODE key to move through the menus and the UP/DOWN keys to select data. At this point, enter the Calibration menu, and select US or SI under the dFL parameter, if necessary. Rate, reset, and °F appear with US, and integral, derivative and °C appear with SI. See Appendix 3, Page 28.

NOTE:

While in the Setup menu, all outputs are OFF.

Figure 18 -The Setup Menu.



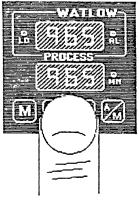


Figure 19 -Entering the Setup Menu.

Entering the Setup Menu

The Setup Menu displays the parameters that configure the Series 965's features to your application.

To enter the Setup Menu, press the UP andDOWN keys simultaneously for 3 seconds. See Figure 19. The lower display shows the LOC parameter, and the upper display shows its current level. All keys are inactive until you release both keys. You can reach the LOC parameter from anywhereexcept the CAL menu.

Use the MODE key to cycle through the menu; use the UP/DOWN keys to select Setup data. You may not see all parameters in this menu, depending on the unit's configuration and model number. After stepping through the menu, you will return to the control set point parameter under the Operation menu.

MACHINE FUNCTIONS UNIT D DETAILS & A D J U S T M E N T S

SECTION 6 TEMPERATURE CONTROLS

Setup Parameters

When you are at the top of the menu, the Series 965 displays the user level of operation in the upper display, and the LOC parameter in the lower display.

When you press the MODE key, the value of the next parameter appears in the upper display, and the parameter appears in the lower display.

Lock: Selects the level of operator lock-out as defined below.

Range: 0 - 4

Default: 0

LOC

LOC 0: All operating parameters may be viewed or changed. Manual operation is permitted. When in manual operation, percent power is adjustable.

LOC 1: The set point and actual are the only visible parameters, set point is adjustable in this level. Manual operation and auto-tune are permitted. When in manual operation, percent power is adjustable.

LOC 2: The set point and actual are the only visible parameters, set point is adjustable in this level. Manual operation is permitted. When in manual operation, percent power is adjustable.

LOC 3: The set point and actual are the only visible parameters, set point is adjustable in this level. Manual operation is not permitted.

LOC 4: The set point and actual are the only visible parameters, set point is not adjustable in this level of lock-out. Manual operation is not permitted.

Input: Selects the sensor input type. Only those input types which are compatible with your unit will appear. See the model number information for your type.

Range: J, K (appears as H), t, n, rtd

Default: J or rtd

In

Celsius _ Fahrenheit: Selects the units of temperature measurement for the control. The default is dependent on the dFL parameter located in the Calibration menu. If dFL = US, the default is F. When dFL = SI, the default is C.

Range: C or F

C or F

Range Low: Selects the low limit of the operating range. See the model number and specification in the Appendix for range values. See Table 1 on Page 16.

Range: Sensor range low to rH

Default: Low limit of sensor type

rL 0°C 32°F

Range High: Selects the high limit of the operating range. See the model number and specification information in the Appendix for your range values. Range: Sensor range high to rL

Default: High limit of sensor type

rН 260°C 500°F

Output 1: Selects the output action for the primary output. Action in response to the difference between set point and process variable.

Range: ht, CL

Default: ht

Ot1 HT

Hysteresis: Selects the switching hysteresis for Output 1 when you select 0 (ON/OFF) under the Pb1 parameter. See Page 17 for the Pb1 parameter.

Range: 1°F - 99°F/1°C - 55°C

Default: 3°F/2°C

HYS 2°C 3°F

SECTION 6 TEMPERATURE CONTROLS

ALt

Alarm Type: Determines whether the alarm type is process, deviation, or none. A process alarm is set at an absolute temperature to prevent over/underrange.

See Chapter 5, "Using Alarms."

Range: Pr. dE, no

Default: Pr

LAt nLA

Latching: Selects whether the alarm is latching or non-latching. Latching alarms must be cleared before the alarm output will reset. Non-latching automatically resets the alarm output when the condition clears. This parameter will not appear if ALt = no.

Range: LAt or nLA

Default: nLA

SIL OFF

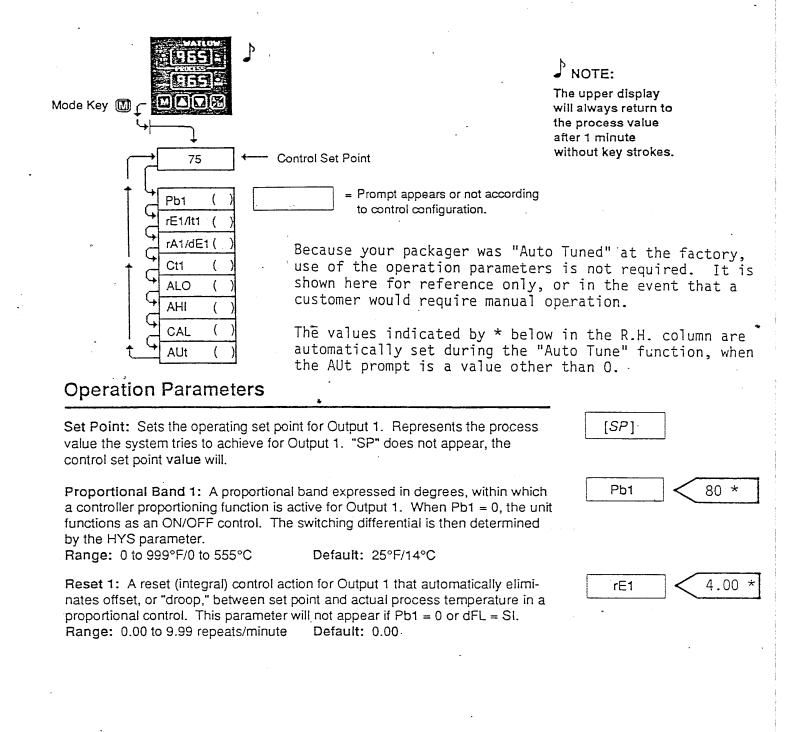
Silencing: Selects alarm silencing (inhibit) for the alarm. This parameter appears only when ALt = dE. For more information see Chapter 5, "Using Alarms."

Default: OFF Range: On or OFF

UNIT D

MACHINE FUNCTION DETAILS & ADJUSTMENTS

SECTION 6 TEMPERATURE CONTROLS



Rate 1: The rate (derivative) function for Output 1 of the Series 965. The rate is determined by how fast the error is changing. This parameter will not appear if Rb 1 = 0 or dEl = St

if Pb 1 = 0 or dFL = SI.

Range: 0.00 to 9.99 minutes

Default: 0.00

rA1

.02 *

UNIT D

MACHINE FUNCTION &ADJUSTMENTS DETAILS

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Ct1

Cycle Time 1: Expressed in seconds for a controller to complete one ON/OFF cycle for Output 1. Time between successive turn ons. This parameter will not appear if Pb 1 = 0.

Range: 1 to 60 seconds

Default: 5

0°C ALO 32°F

Alarm Low: This parameter represents the low process alarm or low deviation alarm. This parameter will not appear if ALt = no or your unit does not have alarms. See the model number.

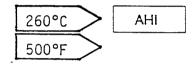
If ALt = dE: Range: 0 to -99°F/0 to -99°C

Default: -99°F/-55°C

If ALt = Pr:

Range: rL to AHI

Default: rL



Alarm High: This parameter represents the high process alarm or high deviation alarm. This parameter will not appear if ALt = no or your unit does not have alarms. See the model number.

If ALt = dE:

Range: 0 to 99°F/0 to 99°C

Default: 99°F/55°C

If ALt = Pr:

Range: ALO to rH

Default: rH

0°C CAL 0°F **AUt** 3

Calibration Offset: Adds or subtracts degrees from the input signal. Range: -180°F to 180°F/-100°C to 100°C Default: 0

Auto-Tune: This parameter initiates auto-tune for Output 1. This parameter

only appears if Ot1 = ht.

Range: 0 = off, 1 = slow, 2 = medium, 3 = fast Default: 0

SECTION 6 TEMPERATURE CONTROLS

How to Tune and Operate

Tuning - Automatic

Auto-tuning: The Series 965 can automatically tune the PID parameters to fit the characteristics of your particular thermal system.

The auto-tuning procedure operates on a thermal response value — slow, medium, or fast. Use the slow thermal response when your process does not need to reach set point too rapidly, or if it usually does not often exceed set point. A fast thermal response produces a rapid temperature change over a short period of time.

You can only auto-tune when Output 1 is heat. Once the auto-tune sequence has begun, the lower display flashes between At and the setpoint. The heat proportional band is set to 0 and the control goes into an ON/OFF mode of control at 90% of the established set point. The displayed set point remains unchanged.

Once the control finishes "learning" the system, it returns to a standard PID control with the heat PID values automatically set as a result of the auto-tuning. Tuning is complete within 80 minutes. Any change of the set point, while in auto-tune, re-initiates the auto-tune procedure.

To start auto-tuning:

- 1. Press the MODE key until the AUt prompt appears in the data display.
- Select a thermal response value, 1=slow, 2=medium, and 3=fast, using the UP/DOWN keys. A thermal response value of 2 satisfactorily tunes most thermal systems.
- Press the MODE key. While the control is in the tuning mode, the lower display alternately displays the normal information and the prompt At. The time between alternations is 1 second.
- 4. When tuning is complete, the displays return to their previous state and AUt reverts to 0. The 965 installs appropriate PID tuning parameters and saves them in the non-volatile memory.

To abort auto-tuning, operator must reset the AUt parameter to 0, or press the AUTO/MAN key twice. The auto-tuning process may also be aborted by cycling the power off and on. In all cases, aborting auto-tune restores all original values.

NOTE:

Set the HYS parameter under the Setup menu to 3°F/2°C before auto-tuning your control.

SECTION 6 TEMPERATURE CONTROLS

Tuning - Manual

For optimum control performance, tune the Series 965 to the thermal system. The tuning settings here are for a broad spectrum of applications; your system may have somewhat different requirements. NOTE: This is a slow procedure, taking from minutes to hours to obtain optimum value.

- Apply power to the Series 965 and enter a set point. Begin with these Operation Parameters: Pb1 = 1, rE1/lt1 = 0.00, rA1/dE1 = 0.00, Ct1 = 5, CAL = 0, AUt= 0.
- 2. Proportional Band Adjustment: Gradually increase Pb1 until the upper display temperature stabilizes to a constant value. The process temperature will not be right on set point because the initial reset value is 0.00 repeats per minute. (When Pb1 = 0; rE1/lt1 and rA1/dE1 are inoperative, and the 965 functions as a simple ON/OFF control.) The HYS parameter determines the switching differential value.
- 3. Reset/Integral Adjustment: Gradually increase rE1, or decrease It1 until the upper display temperature begins to oscillate or "hunt." Then slowly decrease rE1 or increase It1 until the upper display stabilizes again near set point.
- 4. Cycle Time Adjustment: Set Ct1 as required. Faster cycle times sometimes achieve the best system control. However, if a mechanical contactor or solenoid is switching power to the load, a longer cycle time may be desirable to minimize wear on the mechanical components. Experiment until the cycle time is consistent with the quality of control you want.
- 5. Rate/Derivative Adjustment: Increase rA1/dE1 to 1.00 minute. Then raise set point by 20° to 30°F, or 11° to 17°C. Observe the system's approach to set point. If the load temperature overshoots set point, increase rA1/dE1 to 2.00 minutes.
 - Raise set point by 20 to 30°F, or 11 to 17°C and watch the approach to the new set point. If you increase rA1/dE1 too much, approach to set point is very sluggish. Repeat as necessary until the system rises to the new set point without overshooting or approaching the set point too slowly.
- 6. Calibration Offset Adjustment: You may want your system to control to a temperature other than the value coming from the input sensor. If so, measure the difference between that temperature (perhaps at another point in the system) and the process value showing in the upper display. Then enter the CAL offset value you want. Calibration offset adds or subtracts degrees from the value of the input signal.

Manual and Automatic Operation

To change from manual to auto operation, press the AUTO/MAN key twice.

Manual operation provides direct (time proportioned % power) control of the outputs from -100% to 100%. The 965 allows a negative output value only with a CI (Cool) selection on Ot1, a positive output value is allowed with heat only. Automatic operation provides closed loop ON/OFF or PID control. When the operation transfers from a closed loop to an open loop, the 965 retains the power level from the closed loop control. When the 965 returns to the closed loop control, it restores the previous set point temperature.

SECTION 6 TEMPERATURE CONTROLS

D. The preset temperature shown entered in step 21 is arbitrary and can be varied depending on film type used. This temperature cannot be set higher than the "range high" setting (step 11) or the "alarm high" setting (step 31).

STEP	<u>EXPLAINATION</u>	DEPRESS <u>KEY</u>	BOTTOM DISPLAY	TOP <u>DISPLAY</u>
			(SETPOINT TEMP.)	(ACTUAL HEATER TEMP.)
1	After power up the displays will show actual temperature reading from thermocouple (top) and setpoint temperature (bottom). Do not be concerned with the display now as the preset will be made later.	•		
2	Access set up menu by depressing both up and down keys together for 3 seconds, then release. The "lock-out" menu will be displayed.	Both 3 Sec.	LOC	
3	Set "lock-out" to '0' by using either the up or down keys.	△or▽	LOC	0
4	Access "input" menu by depressing the mode key once.	M	In	
5	Set "input" to type 'J' thermo- couple, by using the up or down keys.	△or▽	In	J
6	Access "temperature scale" menu by depressing the mode key once.	M	C _ F	
7	Set "temperature scale" to 'C' or 'F' using the up or down keys.	△or▽	C - F	C or F
8	Access "range low" menu by depressing the mode key once.	M	rL	
9	Set "range low" to '0'for C Deg. or 32 for F Deg. by using the up or down keys.	△or▽	rL	0 or 32
10	Access "range high" menu by depressing the mode key once.	M	rH	
11	Set "range high" to '260' for C Deg. or '500' for F Deg. by using the up or down keys.	△or▽	rH	260 or 500

STEP	EXPLAINATION	DEPRESS <u>KEY</u>	BOTTOM DISPLAY	TOP <u>DISPLAY</u>
12	Access "output 1" menu by depressing the mode key once.	M	Otl	
13	Set "output 1" to 'ht' by using the up or down keys.	△or▽	Ot1	ht
14	Access "hysteresis" menu by depressing the mode key once.	M	HYS	
15	Set "hysteresis" to '2' by using the up or down keys.	△or▽	HYS	2
16	Access "alarm type" menu by depressing the mode key once.	M	ALt	
17	Set "alarm type" to 'Pr' by using the up or down keys.	△or▽	ALt	Pr
18	Access "latching" menu by depressing the mode key once.	M	Lat	
19	Set "latching" to 'nLA' by using the up or down keys.	△or▽	LAt	nLA
2,0	Access "set point" menu by depressing the mode key once.	M		
21	Set "set point" temp. by using the up or down keys	△or▽	Setpoint Temp.	(Actual Temp.)
22	Depress the mode key once, this accesses the "proportional band" menu. Do not be concerned with this as it will be set automatically with the auto-tune procedure.	M	Pb1	
23 : ;	Depress the mode key once. This accesses the "reset 1" menu. Do not be concerned with this as it will be set automatically with the auto-tune procedure.	M	rE1	
· 24	Depress the mode key once. This accesses the "rate 1" menu. Do not be concerned with this as it will be set automatically with the autotune procedure.	M	rA1	

STEP	EXPLAINATION	DEPRESS <u>KEY</u>	BOTTOM DISPLAY	TO P DISPLAY
25	Access "cycle time" menu by depressing the mode key once.	M	ctl	
26	Set "cycle time" to '2' by using the up or down keys.	△or▽	Ct1	. 2
27	Access "alarm low" menu by depressing the mode key once.	M	ALO	
28	Set "alarm low" to '0' for C Deg. or '32' for F Deg. by using the up or down keys.	△or▽	ALO	0 or 32
29	Access "alarm high" menu by depressing the mode key once.	M	AHl	
30	Set "alarm high" to '260' for C Deg. or '500' for F Deg. by using the up or down keys.	△or▽	AHL	260 or 500
31	Access "calibration offset" menu by depressing the mode key once.	M	CAL	
3 2	Set "calibration offset" to '0' by using the up of down keys.	△or▽	CAL	0
33	Access "auto-tune" menu by depressing the mode key once.	M	AUt	
34	Set "auto-tune" to '3' by using the up or down keys.	△or▽	AUt	3
35	To start the auto-tune procedure, press the mode key once. The bottom display will alternate between at and the setpoint temperature until the auto-tune	M	at/Setpoint Temp.	(Actual Temp.)
	procedure is finished.		Setpoint Temp.	(Actual Temp.)
36	Once the "auto-tune" procedure is finished, access the set up menu again by depressing both up and down keys together for 3 seconds, then release. The "lock out" menu will be displayed.	△ ▽ Both	LOC	0
37	Set "lock out" to '3' by depressing the up key 3 times.		LOC	3

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UNIT D MACHINE FUNCTION DETAILS & ADJUSTMENTS

STEP	EXPLAINATION	DEPRESS <u>KEY</u>	BOTTOM DISPLAY	TOP <u>DISPLAY</u>
38	depress the mode key repeatedly until the bottom display shows set point temperature and the top display shows the actual heater temperature.	M	Setpoint Temp.	(Actual Temp.)

^{*} The controller is now programmed and is running. The top display, which is the actual heater temperature should stabilize and be within a few degrees of the setpoint temperature.

SECTION 6
TEMPERATURE CONTROLS

How To Deal With Error Codes

Three dashes, "---" or "rES" (reversed sensor), in the upper display indicate a Series 965 error.

- If operator access is LOC 0, 1 or 2...
 - Press the AUTO/MAN key twice to see the error code for one second.
- If operator access is LOC 3 or 4....
 - The error code is already in the lower display.
- Error code definitions and actions...

Er 1 - Sensor overrange error

The sensor input generated a value higher than that allowed for the range of the sensor, or the A/D circuitry malfunctioned. Enter a valid input. The A/D value is above the range limits, but within the A/D conversion limits. Make sure the In parameter matches your sensor.

Er 2 - Sensor underrange error

The sensor input generated a value lower than that allowed for the range of the sensor, or the A/D circuitry malfunctioned. Enter a valid input. The A/D value is below the range limits, but within the A/D conversion limits. Make sure the In parameter matches your sensor.

Er 3 - Ambient error

Check the specification for the ambient temperature range.

Er 4 - Configuration error

The unit's microprocessor is faulty; call the factory.

Er 5 - Non volatile checksum error

The nonvolatile memory checksum discovered a checksum error. Unless a momentary power interruption occurred while the unit was storing data, the nonvolatile memory is bad. Call the factory.

Er 6 - A/D underflow error

The A/D circuit is underrange. An open or reversed polarity sensor is the most likely cause. Check the sensor; if the connection is good and functions properly, call the factory. The A/D underrange voltage is too low to convert an A/D signal. Make sure the In parameter matches your sensor.

Er 7 - A/D overflow error

The A/D circuit is overrange. An open or reversed polarity sensor is the most likely cause. Check the sensor; if the connection is good, and the sensor functions properly, call the factory. The A/D overrange voltage is too high to convert an A/D signal. Make sure the In parameter matches your sensor.

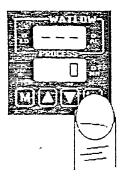
- To clear a corrected error...
 - Cycle power to the control.



Electrical noise or a noise event, vibration or excess environmental moisture or temperature may cause Series 965 errors to occur. If the cause of an error is not otherwise apparent, check for these.

Figure 22 -Error Code Display Examples

Press twice - Read error





SECTION 6 TEMPERATURE CONTROLS

Er 1, 2, 3, 6 & 7 Errors - Control Outputs May Be ON

If operator access is LOC 0, 1 or 2...

...and the control was in AUTO operation when the error occurred, it goes into MANUAL (% power) operation. If the output power is less than 75% power, and a <5% change in power occurred within the last two minutes, the 965 switches into Manual operation at the last Automatic power level. If the control was in MANUAL operation, it remains there. (You must press the AUTO/MAN key twice to see the error code.) The alarm output (if present) is in its alarm state (LED lit). The upper display reads "---" or rES. The lower display indicates the error code.

If the control was operating with stable output values when the error occurred, it continues to operate at those levels on a % power basis. If output values were not stable, the control outputs go to 0% power (OFF).

If operator access is LOC 3 or 4...

The control remains in AUTO operation. The control outputs shut OFF. The AUTO/MAN and MODE keys are inactive. The UP/DOWN keys may be used together to enter the Setup Menu. The alarm output (if present) is in its alarm state (LED lit). The upper display reads "---" or rES. The lower display indicates the error code.

- To clear a corrected error...
 - Cycle power to the control.

Er 4 & 5 Errors - Control Outputs Will Be OFF

- Error codes Er 4 and Er 5 result in these conditions:
 - The control is in AUTO operation with the output OFF.
 - The alarm output, if present, is in the alarm state (de-energized with the LED lit).
 - · The upper display indicates the process value.
 - The lower display indicates the error code.
 - All keys are inactive.
 - All Setup Menu parameters return to default values.
 - The above conditions occur regardless of the value of LOC, or the presence of the Setup or Calibration Menus.

To clear a corrected error...

. • Cycle power to the control.

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MACHINE FUNCTION DETAILS & A D J U S T M E N T S

SECTION 6 TEMPERATURE CONTROLS

The MAN LED indicates auto or manual operation. When the LED is ON, the control is in Manual operation. When the LED is OFF, the control is in AUTO operation. When the LED flashes, press the key again within five seconds to complete the change in operation. If the sensor is open and LOC = 0, 1 or 2, the Series 965 switches to Manual operation (time proportioned % power), if the output was stable before the break occurred.

When transferring from auto to manual operation, the control output(s) remain stable ("bumpless," smooth transition). When transferring from manual to automatic operation, the control output(s) may change significantly. In manual, the output value (% power) appears in the lower display. In automatic operation, the set point appears.

NOTE:

When the alarm output is de-energized, the N.O. contact is open in the alarm condition.

NOTE: IN THE EVENT OF A THERMOCOUPLE FAILURE THE CONTROL WILL SHUT DOWN, DISCONTINUING PACKAGER OPERATION. MANUAL MODE CAN BE USED TO GET UP AND RUNNING AGAIN-CONSULT RENNCO SERVICE. WARNING: OPERATION OF THE CONTROL ABOVE 30% IN THE MANUAL MODE COULD DAMAGE SEAL BLADES.

Using Alarms

The Series 965 has two alarm types, Process or Deviation. A Process alarm sets an absolute temperature when the process exceeds that absolute temperature limit. Process alarm set points may be independently set high and low.

A Deviation alarm alerts the operator when the process strays too far from set point. The operator can enter independent high and low alarm settings. The reference for the deviation alarm is the set point. Any change in set point causes a corresponding shift in the deviation alarm. Example: If your set point is 100°F/38°C, and you have a deviation alarm set at +7°F/4°C as the high limit, and -5°F/3°C as the low limit, the high alarm trips at 107°F/41.6°C, and the low alarm at 95%F/35°C. If you change the set point to 130°F/54.4°C, the alarms follow the set point and trip at 137°F/59°C and 125°F/51.6°C.

Alarm Silencing is available with the deviation alarm. When SIL is selected as "on," the non-latching mode automatically enables the alarm out-put on initial power up. In the latching mode, the operator must manually disable the alarm by pressing the AUTO/MAN key once. In both cases alarm silencing disables the alarm output relay, but the AL LED displays the alarm condition until the process value is within the "safe" region of the deviation alarm band. Once the process value crosses into the "safe" region, both a latching or a non-latching alarm is ready. Any future deviation outside this safe band triggers an alarm.

Both Process and Deviation alarms can be latching or non-latching. The operator must manually reset a latching alarm before the alarm will reset. The operator must also remove the condition that created the alarm. When the operator removes the condition causing the alarm, a non-latching alarm automatically resets the alarm output.

Flashing 'LO" or "HI" in the lower display indicates an alarm. The Lower display alternately shows information from the current parameter and the "LO" or "HI" alarm message at one second intervals. The alarm output is de-energized and the AL LED is lit.

To clear an alarm...

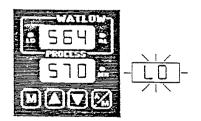
- First correct the alarm condition, then...
 - If the alarm is latching... Clear it manually; press the AUTO/MAN key once as soon as the process temperature is inside the alarm limit by 1°F/0.6°C.
 - If the alarm is non-latching... The alarm clears itself automatically as soon as the process temperature is inside the alarm limit by 1°F/0.6°C.



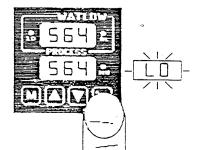
CAUTION:

An alarm display will be masked by an error condition or when the control is in the Calibration or Setup Menus.

Figure 21 -Alarm Display Examples



Press once -Clear a latched and corrected alarm.



SECTION 6 TEMPERATURE CONTROLS

STEP BY STEP INSTRUCTIONS FOR REPLACEMENT AND/OR PROGRAMMING OF CONTROL.

The following section explains a procedure that will allow the controls to be set up and tuned by persons unfamiliar with them. It is simply an extension of the information given in previous sections but put in a step by step format

Section I deals with replacing a defective control with a new one. This section can be bypassed if the only objective is to set up the control menu of an existing unit. Section II can be used to either set up a new control or to step through the menus of an existing control to verify or change contents.

Read Notes and Cautions Section before stepping through the menus.

I. Replacing a controller.

Turn off power to the packager. Remove the heater control insert circuitry from the outer case by releasing the latches on both sides of the face of the control and then sliding it out of the case. Remove the new control insert from it's case and slide it in.

*Since all the wiring for the control is to the outer case, the electrical enclosure door will not even have to be opened to replace this unit.
Turn "on" power to packager.

II. Setup control menu.

*Notes and Cautions

- A. After the set up menu is accessed (step 2 or step 37), if at any time during programming, no keys are depressed in a period of 1 minute, the control automatically goes back to step 1. Programming will have to be started again at step 2, although the menu items already programmed will stay where they were set.
- B. When stepping through the menu items, if they are already set up with the correct presets, it is not necessary to use the up or down keys to change them.
- C. CAUTION: When accessing the menu, do not hold the up and down keys any longer than necessary to access the desired menu (see step 2 or step 37). Once this menu is accessed release the keys, as eventually the calibration menu is accessed. If the calibration menu is altered it would require sending the control back to the Watlow factory for reprogramming. If the calibration menu is accessed accidentally, exit this menu by repeatedly pressing the mode key.

SECTION 6 TEMPERATURE CONTROLS

6.2.1 BACK UP HEATER CONTROL \$300-8AC

The heated silicone back up rubber applies heat to the side of the film opposite the seal bar allowing seals to be made at a lower seal bar temperature. This helps reduce film build up on the blades..

The operating temperature should be between 105 deg. F and 165 deg. F (66 deg. C to 74 deg. C) as measured on the sealing surface of the teflon tape covering the silicone back up rubber. The voltage source for the heater is a controller that supplies a constant voltage. The voltage required to make the heater operate at the above temperature is indicated on a label along side the controller. This voltage is factory preset but may need slight adjustment depending on main power line voltage. To check and verify voltage level, place meter leads on terminals "A" and "B" of the terminal strip in the lower part of the electrical enclosure. If adjustment is necessary, turn the main pot while reading voltage at terminals "A" and "B" until desired voltage is achieved. (If desired temperature cannot be reached, read installation and tuning procedure below.)

CAUTION: Operating the back up heater at temperatures higher than shown above may damage back-up jaw components.

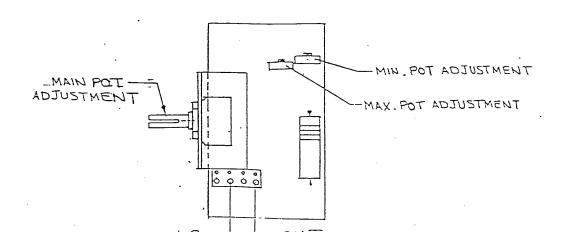
INSTALLATION AND TUNING OF A REPLACEMENT BACK UP HEATER CONTROL.

When installing a new back-up heater control it must be tuned to the model of machine it is installed in. First turn off the power and wire the control. Locate all the adjustment pots (Main, Min. and Max. in figure below) and turn all counterclockwise to off position. Attach meter leads to terminals L2 and out on control terminal junction or to "A" and "B" terminals at rear of electrical enclosure.

Turn power on and turn main pot stem to full clockwise on position. (meter should read near zero voltage) adjust Max. pot screw clockwise until the voltage reading on the meter reaches the voltage indicated on the back-up heater label on the control panel door.

If the voltage required on the label cannot be obtained by the setting procedure above then the Min. pot. adjustment screw will have to be turned clockwise until correct voltage is reached.

See Page 56B for voltage set point and maximum voltage requirement.



UNIT D

M A C H I N E F U N C T I O N D E T A I L S & A D J U S T M E N T S

MODEL 101	TEMP. 150°F/66°C	DON'T EXCEED
HTR. SIZE	SET VOLTS	MAX. VOLTS
8" x 20"	20 to 21	24
14" x 20"	20 to 22	26

MODEL 201	TEMP. 150°F/66°C	DON'T EXCEED
HTR. SIZE	SET VOLTS	. MAX. VOLTS
8" x 10"	11 to 12	14

MODEL 401	TEMP. 150°F/66°C	DON'T EXCEED
HTR. SIZE	SET VOLTS	MAX. VOLTS
14" x 36"	30 to 31	38
18" x 36"	34 to 35	44

MODEL 501	TEMP. 150°F/66°C	DON'T EXCEED	
HTR. SIZE	SET VOLTS	MAX. VOLTS	
8" x 42/52"	40 to 41	50	
14" x 42/52"	45 to 46	56	
18" x 42/52"	52 to 53	62	

SETTING INSTRUCTIONS FOR THE BACK-UP HEATER CONTROL R101-1060B

Before wiring control turn both potentiometers counter-clockwise to off position. (Remove horizontal and vertical heater fuses.) After wiring control connect digital voltage meter to terminals A & B at the back panel terminal strap.

Turn power on and adjust main potentiometer screw to full open setting. (If this setting exceeds the maximum 12.5 volts for the 201 machine adjust main pot to 12.5 volts and lock stem nut.) If the voltage reading is less than required for your machine (see chart below) turn the main pot screw back 1/8 turn and adjust the trim potentiometer screw slowly clockwise until proper voltage is reached. Do not exceed maximum in chart. Lock stem nut on main pot and replace heater fuses.

MACHINE MODEL	MAXIMUM VOLTAGE
101	23 to 25
201	11.5 to 12.5
401	36 to 38
501	44 to 46

The silicone back-up temperature should be between 145° & 165° for polyethelene films. You should be able to touch the back-up with your hand for a few seconds before it becomes to uncomfortable. If not, the temperature is excessive. Check with pyrometer and adjust back-up heater control until you can touch with your hand for a few seconds.

CAUTION: Excessive temperature may produce poor seals, film sticking to back-up, ruin back-up silicone and "H" channel extrusion.

NOTE: When running shrink films a lower back-up temperature may be required (or no temperature) to produce more adequate seals. Adjust heater control to suit film used.

SECTION 6 TEMPERATURE CONTROLS

6.3 TEMPERATURE CONTROL SYSTEM TROUBLESHOOTING

The control is designed to be able to give indication of possible problems and to shut down the outputs to the heaters. This is necessary to protect the heater blades which have a release coating that will be damaged by an overtemperature condition.

The range high (RH) and Alarm High (AHI) parameters ensure that an electrical fault will not drive the temperature of the jaws beyond an acceptable unit. See "How to Deal with Alarms". Error codes indicate other problems that may be diagnosed as thermocouple failures, or problems with the controller circuitry. In both of the above cases, the output power to the heater is turned off until the problem is found and corrected.

Manual operation (not to be confused with manual tuning) is used in an emergency situation when an alarm or error code shuts down the control, but due to production requirements the equipment must be kept running temporarily until there is time to fix the problem. See "Manual and Automatic Operation". An approximate Percent Power Value to use in this case would be 75%. This value can then be adjusted further to suit the particular films and speeds, to arrive at the best seals. After the problem has been corrected, the controller can be put back into the automatic operation mode.

If a sudden significant raise in operating temperature is required to maintain good sealing characteristics, it may be possible the back-up heater is not operating. It can be checked by locking the jaws open, and disconnecting the air supply, then feeling of the back-up rubber. It should be warm enough that it will be uncomfortable or impossible to keep your hand in contact with it for any length of time. If unsure as to whether or not it is operable, disconnect the electrical supply to the machine, then remove the back-up heater lead wires. Perform a continuity check on the heater to determine if it has an open circuit.

PROGRAMMABLE CONTROLLER (PC)
REFER TO UNIT A, SECTION 3.9 FOR COMPONENT IDENTIFICATION

7.1 <u>DESCRIPTION OF PROGRAMMABLE CONTROLLER</u> The PC is used to control the sequence and functions of the machine. It does so by reading the conditions of inputs (switches, electric eyes, relay contacts, etc.) and thumbwheel switches, processing the information, then turning on the appropriate outputs to the valves or other controlling components.

The main components of the PC are:

A. The Base G.E. Unit controlling inputs and outputs. In addition, 24 volt power terminals are available for powering input devices such as proximity switches or electric eye sensors.

The central processing unit (CPU) is the "brain" that sets the control logic and interacts with the "Prom" memory chip to make the machine cycle. The condition of the CPU can be known by checking the diagnostic led's at the left end of the PC. Refer to the trouble-shooting section of the manual for details.

The input and output terminals receive signals indicating the input status and send signals to control the packager movements.

In most applications the packager is supplied with a "Prom" chip. This is a fixed program which cannot be altered with the use of a programmer and which does not rely on the battery in the PC so the battery is not important. (The battery in the PC is used only for retaining the program when the ram memory is used.)

B. Thumbwheel Timer/Counter Set Point Unit This plug-on unit allows adjustable timing for "jaw safety," "heater
dwell," "auto-cycle" and "seal cooler" functions. Refer to UNIT D,
SECTION 7.3 for explanation of timers.

SECTION 7 PROGRAMMABLE CONTROLLER (PC)

7.1 DESCRIPTION OF PROGRAMMABLE CONTROLLER, Continued

C. Prom Memory Chip
The prom memory chip stores the program for the sequence of machine functions. The program is standardized for most packager models. Options that require functions and timings other than the standard program are "hard wired" in, in the form of separate relays, timers, switches mounted in the electrical enclosure. In most cases the signals back and forth to the options are interfaced by using existing input and output terminals of the PC.

The program name is written on a label attached to the prom chip itself. The name is normally given as prom #1, prom #14, etc. When replacing a defective prom chip, it must be replaced with one bearing the same program name. These are available through Rennco only.

7.2 CYCLE SEQUENCE The following sequence description is for a standard packager without options. It is intended as a guide in understanding how the different packager functions relate to each other. Options that require interfacing such as infeed systems may alter the overall sequence as described here.

INITIAL CONDITIONS:
Main Power Switch "on"
Air Supply to Valves "on"
Trim Wind-Up Switch "on"
Jaws are closed

PALM SWITCH IS DEPRESSED

This sends an input to the PC, which in turn sends an output to the JAW OPEN solenoid of the main drive valve. At the same time, a signal is sent to the FILM ADVANCE solenoid which advances the film.

NOTE: There is a built-in delay of approximately .1 second, after the jaws start to open before the film starts to feed (film feed delay.)

SECTION 7 PROGRAMMABLE CONTROLLER (PC)

7.2 CYCLE SEQUENCE, Continued

JAWS ARE FULLY OPEN/FILM IS FULLY ADVANCED

The packager is equipped with a limit switch which is actuated when the film feed cylinder is fully extended (film fully advanced). This "Film Advanced" switch must be actuated before the jaws can close. If packager is equipped with optional film registration electric eye. The eye must see the film mark before the jaws close. This feature ensures that the product will be below the jaws before they close. It also makes it possible to adjust film advance speed without having to make jaw speed adjustments for correct timing.

In some high speed applications it is necessary to "by pass" the film advanced proximity switch. In doing so, the jaws will close automatically at a time which is fixed in the program, regardless of the condition of the film advance. Because of this fixed time, it is necessary to make the jaws open fast enough, and the film feed fast enough that the product is out of the way when the jaws close. Also, slowing down the jaw speed closing will allow more time to move the product below the jaws.

In order to by pass the film advanced switch, a jumper wire may be installed form a "common" terminal to the "film advanced" input terminal.

It is desirable, whenever possible, to operate the machine with the "film advanced switch in use. It saves confusion in making cylinder speed adjustments.

JAWS START TO CLOSE

As the jaws start to close, the safety timing begins. When the jaws become fully closed and actuate the "jaws closed" switch the safety timing is terminated. NOTE: Model 401 and 501 packagers are equipped with 2 jaws closed switches, one at each end of the horizontal jaw. Both switches must be actuated to terminate the safety timing. The setting of the "safety adjustment" thumbwheel timer should be done so that the time set is slightly longer than the time it takes for the jaws to close. See UNIT C, SECTION 4.1.

JAWS ARE FULLY CLOSED/HEATERS ADVANCE

The "jaws closed" switch is actuated which in addition to terminating the safety timing, sends a signal to the PC to advance the heaters. The signal goes to the "heater dwell" thumbwheel timer. The heaters advance and dwell advanced for what ever period the timer is adjusted for and then retract.

HEATER RETRACT

At the same time the heaters start to retract, the PC starts the "seal cooler" thumbwheel timing. Its time period should be long enough to help cool the seal, but not so long that too much air is blown at the heaters which would cool them down. After the seal cooler blast stops, the cycle can be repeated.

SECTION 7 PROGRAMMABLE CONTROLLER (PC)

7.2 CYCLE SEQUENCE, Continued

AUTO CYCLE OPERATION

If the auto cycle feature is being used, the cycle will repeat starting immediately after the seal cooler stops if the auto cycle thumbwheel timer is set at its low setting or, it can be adjusted higher to slow the cycle rate.

7.3

- CONTROLS AND TIMING ADJUSTMENTS
 A. JAW LOCK OPEN/SAFETY RESET -JAW CLOSE (101 AND 201 PACKAGERS) Large red push-button located in operator panel of control box. Tap to manually lock the jaws open. Hold one second to reset the safety so the jaws can close. CAUTION: The jaws will close when releasing the push-button after it has been held depressed longer than one second.
- JAW LOCK OPEN/SAFETY RESET-JAW CLOSE (401 AND 501 PACKAGERS) The jaw lock open is a red push-pull switch located on the operator control panel of the control box (401) or in a push button box mounted on the front of the packager (501). The safety reset-jaw closed is a yellow push button located on the operator panel of the control box (401) or in a push button box mounted on the front of the packager (501). To lock the jaws open push in on the jaw lock open switch. To close the jaws or reset the safety, the jaw lock open switch must be pulled out and then the safety reset jaw close switch must be depressed. NOTE: The jaws will not open or close if the safety door is not closed completely.
- MANUAL CYCLE (Palm Switch) Tap once to cycle the machine. Jaws will stay open as long as switch is depressed.
- HEATER EXTEND TOGGLE SWITCH When turned "on", the heaters will extend and remain extended, for the purpose of cleaning or checking alignment, etc. NOTE: The jaws will not close as long as the heaters are extended.
- HEATER DWELL TIMER Adjust so that the heater dwell in the extended position for a short time before they retract. The thinner the film, the shorter the dwell period required. If heater cylinder advance speed is adjusted, it will affect the dwell timer adjustment.

Heater dwell time is approximately equal to 1/60th second x thumbwheel setting. Adjust only the two R.H. thumbwheels. The two L.H. thumbwheels <u>must remain set</u> at "0" for the heater dwell timer to function properly.

SECTION 7

PROGRAMMABLE CONTROLLER (PC)

7.3 CONTROLS AND TIMING ADJUSTMENTS, Continued

E. JAW OPEN DWELL TIMER This thumbwheel timer is used to adjust the amount of time that the jaws stay in the open position. Timing starts when the jaws begin to open. Adjust the timing so that the jaws are able to fully open before they start to close.

NOTE: Jaw Open Dwell Time is equal to .1 second x thumbwheel setting. Adjust only the two R.H. thumbwheels. The two L.H. thumbwheels <u>must remain set at "0"</u> for the jaw open dwell to function properly.

F. AUTO CYCLE DELAY TIMER
Timing begins after the seal cooler stops. The jaws are signaled to open after the timer is timed out.

NOTE: Auto cycle delay time is equal to .1 second x thumbwheel setting. Adjust only the two R.H. thumbwheels. The two L.H. thumbwheels <u>must remain set at "0"</u> for the auto cycle delay timer to function properly.

Adjusting Procedure: With jaws closed and the thumbwheel set to "0", manually cycle the palm switch. The jaws should lock open. Now alternately reset the safety push-button, while turning the thumbwheels up one digit at a time until the jaws finally stay closed. NOTE: The safety timer should be re-adjusted whenever the cylinder speed of the jaws closing is changed. Refer to the standard packager instruction manual for adjustment of the screw that actuates the "jaws closed" switch.

NOTE: Safety time adjustment is equal to .1 second x thumbwheel setting. Adjust only the R.H. thumbwheel. The three L.H. thumbwheels must remain set at "0" for the safety timer to function properly.

H. CYCLE COUNTER

The signal to increment the totalizing cycle counter comes at the time that the heaters start to advance. So if the packager goes into reset, the heaters do not advance, and the counter is not incremented.

UNIT D

MACHINE FUNCTIONS DETAILS & ADJUSTMENTS

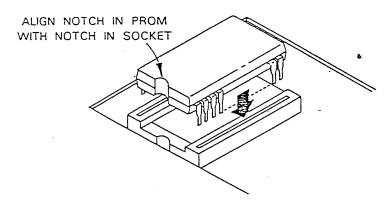
SECTION 7 PROGRAMMABLE CONTROLLER (PC)

I. SERVICING THE PC (FOR SERIES ONE JUNIOR)

The only service to perform on the G.E. Series One Junior is if the prom chip needs to be changed or added, or if the timer/counter access terminal needs to be added or removed.

To insert a prom into the socket, line up the notch in the prom chip to the notch in the socket, and make sure all the terminal pins line up with their respective holes.

If during troubleshooting an electrical problem, it is determined that the PC is defective, it will be necessary to change the entire PC. There are no replaceable modular components.



PROM ORIENTATION INTO SOCKET

SECTION 7 PROGRAMMABLE CONTROLLER (PC)

SERVICING THE PC I. Removing Modules:

Turn main power off and disconnect power cord.

2.

Disconnect any wiring that goes directly to the module. Squeeze the module at the front top and bottom to release the securing tabs.

4. Pull module straight out.

- If replacing CPU module, the prom chip must first be installed with 5. circuit board mounted switches and jumpers set correctly.
- Insert new module aligning circuit boards first into bottom tracks. 6.

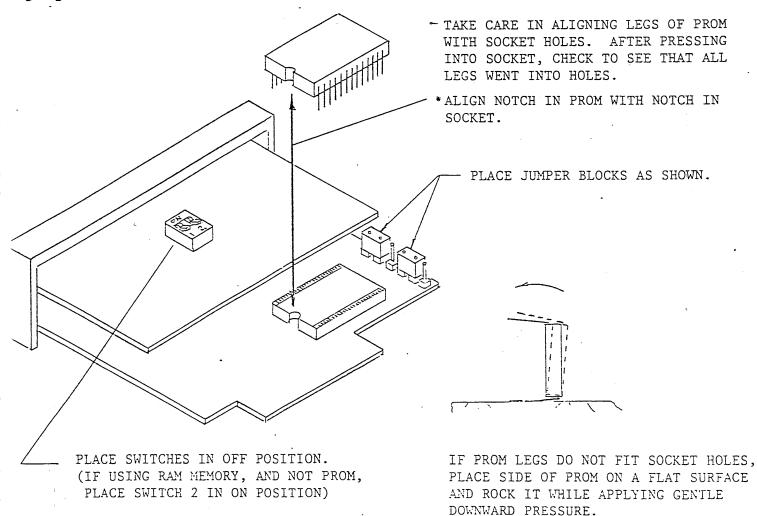
Rotate module upwards slightly to engage top tracks. 7.

Push module into base unit until both tabs snap into place. 8.

Replace any wiring that was removed. 9.

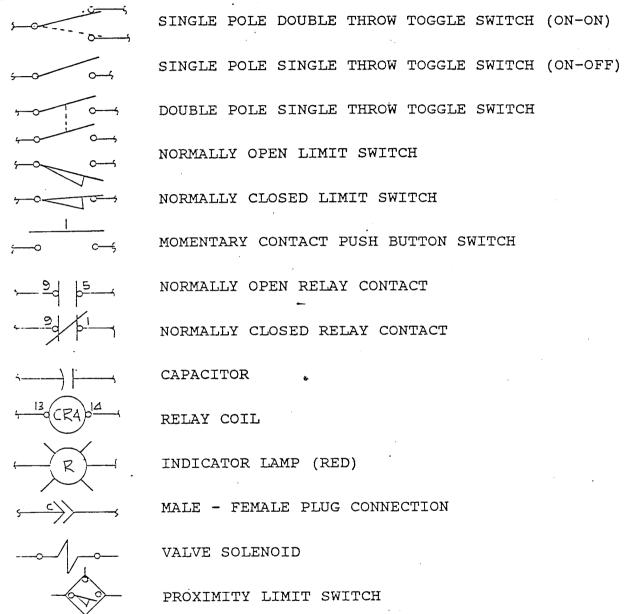
Re-apply power. 10.

Preparation of CPU Module includes setting board mounted switches and placing jumpers in their correct position.



SECTION 7 PROGRAMMABLE CONTROLLER (PC)

7.4 ELECTRICAL CIRCUIT DRAWING DESCRIPTION



- *Switches and relay contacts as they appear on the circuit drawing are shown in their normal, unactuated condition.
- *Numbers adjacent to relay coils and contacts indicate the terminal number of the socket the relay mounts in.
- *Letters adjacent to plug connections indicate the pin designation of the connector body.

SECTION 8 AIR SYSTEM

REFER TO UNIT A, SECTION 3.10 FOR COMPONENT IDENTIFICATION

8.1 <u>DESCRIPTION OF VALVE MANIFOLD ASSEMBLY</u> The manifold assembly consists of a series of manifold base blocks whose supply and exhaust air passages are common through the length of the assembled blocks. However, because certain functions of the machine are operated at lower air pressure than others, blocking discs are used between certain blocks to segregate the two operating pressures. If the base blocks are ever disassembled, care should be taken to not loose the discs nor install them in the wrong ports.

Mounted on top of the base block is the "speed control" interface block which is used to control the exhaust of the cylinder. This is done with metering screws located at each end of the speed control block. Turning the screws clockwise slows the cylinder speed. Each of the screws controls the speed of air leaving one end of the cylinder. The screw is marked with an "A" or "B" which relates to the output port of the valve.

Some machine functions such as the 40 PSI - 80 PSI selector, or hole punch cylinder do not require the speed control block.

The valve itself is either a direct or pilot assisted solenoid spool valve depending on packager model. Direct solenoid valves are capable of operating at air pressures as low as 10 PSI (models 101,401,501,501-36). Pilot assisted solenoid valves (model 201) are capable of operation at no lower than 20 PSI. In applications not requiring high speeds, the regulators can be set somewhat lower than the normal 40 and 80 PSI for 101, 201, and 501, and 20 and 40 PSI for 401. This will reduce air consumption somewhat and more importantly lower the cylinder forces which will lessen the damage to something that gets caught between the jaws.

NOTE: In resetting the regulators lower, make sure that the gripping force of the jaws is still good enough to maintain good seals. It will probably be necessary to adjust the "safety" and "heater dwell" timers.

At each end of the valve are manual override buttons that can be used to operate the spool in the valve, which is helpful in troubleshooting.

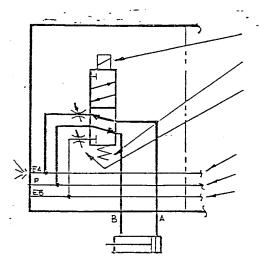
8.2 <u>CYLINDER SPEED AND CUSHION ADJUSTMENTS</u> A label is added to each end of the valves using speed control blocks. The label refers to the function being controlled by the speed control screw at that end of the speed control block.

In making cylinder speed adjustments on "jaw closing" and "heater advance" functions, it may be necessary to readjust the "safety" and "heater dwell" thumbwheel timers. In any case, adjust cylinder speeds in such a way that the machine cycles smoothly.

The main drive cylinder is equipped with adjustable cushions that slow the cylinder during the last 1/2" of travel. Adjust the cushions to keep the jaws from banging at the end of their stroke. NOTE: It is possible to adjust the cushion that affects the jaws closing to be too slow. This may result in the packager going into safety or the heaters starting to advance before the jaws are completely closed and gripping the film.

SECTION 8 AIR SYSTEM

8.3 AIR CIRCUIT DRAWING EXPLANATION



SOLENOID END OF VALVE

SPRING RETURN END OF VALVE

FLOW CONTROL FOR CYLINDER SPEED

(INTERFACE SPEED BLOCK)

COMMON "A" EXHAUST PASSAGE COMMON AIR SUPPLY PASSAGE COMMON "B" EXHAUST PASSAGE

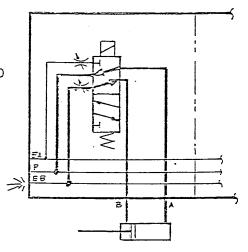


FIGURE 29A

FIGURE 29B

Figure 29A shows a valve and cylinder as they might appear on the air circuit drawing. It is shown in its normal or unactuated condition, which is how all valving is shown on the air circuit drawing. Supply air is routed to the nose end of the cylinder holding it retracted. Exhaust air from cap end of cylinder would have exhausted back through port "A" of the valve through the flow control to the common "A" exhaust passage of the manifold base blocks.

Figure 29B shows what happens when the solenoid is energized. Supply air is routed to the cap end of the cylinder to extend it. The valve spool is shifted against the return spring resistance. Exhaust air should now be routed back to port B of the valve through the flow control to the common "B" exhaust passage. The valve and therefore the cylinder will remain in this condition until the solenoid is de-energized. At that time the return spring would return the valve spool to its original position and the resulting air flow should again be as shown in Figure 29A.

The repositioning of the valve symbol boxes in Figure 29B showing the change in air flow must be imagined as only one operating condition can be shown on the drawing.

UNIT E CAUTIONS & WARNINGS

(Failure to observe can cause damage to machine and/or injury to WARNING: personnel)

*Do not bypass or cut the ground lug off the power cord plug.

*Do not place hands or fingers near moving machine parts. Have hands in full view at all times.

*Do not have one person operate the machine while another is making mechanical adjustments. Specific areas for concern are:

The opening between the jaws

Safety timing adjustment 2)

The linkage arms that move the jaws 3)

The internal jaw parts (moving heater frame) 4)

Film feed mechanism

Areas where moving machine parts contact and actuate fixed switches

Trim wind up spinning spool

ALWAYS disconnect air and electric power sources when working on internal machine parts.

(Failure to observe can cause damage to equipment) CAUTIONS:

*Over oiling air system will eventually lead to malfunctioning of valves

*Dirty, moisture laden air can cause damage to valving

*Refer to maintenance schedule for necessary lubrication
*Continual jamming of products in the jaw area can lead to misalignment
*Programmable controller inputs are 24 volt DC and outputs are 120 volt AC.

Do not make direct connection between inputs and outputs.

*Take extreme care in changing a prom memory chip to not damage legs of chip. *Do not adjust back up heater control beyond voltage stated. (see back-up heater control adjustments. Unit D Section 6.2.1)

UNIT F TROUBLESHOOTING

SECTION 1 GENERAL ELECTRIC TROUBLESHOOTING

Remember that input terminals are 24 volt DC and output terminals are 120 volt AC.

The following process of elimination should help to isolate most problems.

Verify that air and electric power is on, that machine is not in safety, and there is no mechanical binding.

Check condition of main power fuse.

Check CPU module:

If "power" LED is not lit, the P.C. may have to be replaced.

If "CPU" LED is on, the unit may have to be replaced.

If "run" LED is off, the unit is program, load or tape mode, and needs to be put back into run mode.

If the machine has stopped with some outputs energized or basically stopped in mid-cycle, check condition of input and output LEDs. Look for LEDs that should be on but are not and also LEDs that are on that should not be.

If an input is not being received check the condition of the device. it is a switch, make sure the switch actuator is in position and capable of actuating the switch. If it appears the switch should be actuated but no input is being received, check the condition of the switch. mechanical switch, disconnect the lead wires and use an ohmmeter to check continuity through the contacts. If it is a proximity switch or electric eye, remove the lead wire from the input terminal. Use a volt meter to check the operation of the switch by putting the negative (-) lead to the wire from the switch and the positive lead (+) to the +24 volt terminal of the P.C. power supply terminals. If the proximity switch or eye is working correctly, the meter will read 24 volts when the device is actuated.

Outputs should be checked as follows:

If output LED is on but valve coil or relay coil is not functioning, check output fuse then use a volt meter to verify that there is power at the If there is power, replace the valve or relay.

If the output LED is off but should be one, or if the LED is on but there is no power at the coil, replace the output module.

If the correct inputs and outputs are present and the valve is not operation as it should, replace the valve. If valve seems to be operating correctly, but the cylinder is not reacting as it should, check to see if cylinder is worn out and "blow by" is occurring. This is when the piston seal is damaged and air is blowing past it. The usual indication of this is constantly expending a simple constantly expensive const is constantly exhausting air when the machine is at rest. It can be verified by removing the air line from the cylinder port opposite of the end that is pressurized. Air will bleed out of this port if the cylinder is defective.

The manual overrides at the valve solenoids can be used in the troubleshooting to check cylinder operation.

PAGE

69

POSSIBLE CAUSES

HEATER IS BLOWN OUT THERMOCOUPLE IS DEFECTIVE TEMPERATURE CONTROL IS IN ANY OF SEVERAL ALARM OR ERROR CODE MODES
3.5.
HEATER WILL NOT HEAT UP OR S UNCONTROLLABLE

1. FILM FEED ROLL SET SCREW LOOSE 2. CYLINDER DEFECTIVE 3. FEED SPROCKET CLUTCH SLIPPING 4. PC OR VALVE DEFECTIVE

ILM WILL NOT ADVANCE

PU UK VALVE DEFECTIVE	HEATER FRAME IS BINDING "JAWS CLOSED" SWITCH OUT OF	"HFATER DWELL" TIMER NOT SET
ر S	HEATER "JAWS ADJIIST	"HFATE
•		~

WILL NOT ADVANCE OR

HEATERS RETRACT

PROPERLY

·	"HEALER DWELL LINER NOT SE
	PROPERLY
	PC OR VALVE DEFECTIVE

;	MECHANICAL BINDING IN JAWS
?	SAFETY THUMBWHEEL LIMER SEI
	INCORRECTLY
	"JAWS CLOSED" SWITCH OUT OF
	AD HISTMENT

AND AND

JAWS STAY EITHER CLOSED VON'T OPEN OR STAY OPEN VON'T CLOSE

"FILM ADVANCED" SWITCH DEFECTIVE

4.

. 🚅	"JAWS CLOSED" SWITCH ACTUATOR BOLT
2.	"SAFETY" THUMBWHEEL TIMER OUT OF
3,	ADJUSIMENI THUMBWHEEL MAY BE DEFECTIVE

JAW SAFETY WILL NOT ACTIVATE WHEN SOMETHING GETS CAUGHT IN

JAWS

 CHECK CONTINUITY (CHECK CONTINUITY OF LEAD WIRES TO VERIFY AN
OPEN CIRCUIT THEN	OPEN CIRCUIT THEN REPLACE THE HEATER

~	IF THERMOCOUPLE IS AN OPEN CIRCUIT, THE
i	9
	THE THERMOCOUN
	OF THE HEATER THE HEA
	LEGKAL FANT OF THE HEATENS THE
	WILL HAVE TO BE REPLACED

. 0

SEE SECTION 6.2

TIGHTEN SET SCREW	CHECK FOR "BLOW BY"	REPLACE CLUTCH
•	٠.	~

[.] SEE GENERAL TROUBLESHOOTING

3. READJUST TIMER

BIND	
ECTE	
CORRECT	

^{3.} CHECK THUMBWHEEL BY CHANGING IT TO A LOW NUMBER (2 OR 3). IF SAFETY STILL DOESN'T ACTIVATE, REPLACE THUMBWHEEL INTERFACE MODULE OR THUMBWHEEL SWITCH ASSEMBLY.

POSSIBLE CAUSES

PROBLEM

TURN RUBBER TO A FRESH SURFACE OR REPLACE RUBBER CHECK CONDITION OF BLADE. REPLACE IF THE EDGE IS DAMAGED OR IF THE RELEASE COATING IS NOT KEEPING THE MOLTEN FILM FROM BUILDING UP SEE SECT. 5.4 SEE SECT. 5.2	TIGHTEN SET SCREW CLEAN THE ROLL REPLACE CLUTCH CLEAN OR REPLACE BRAKE	REPLACE FUSE CHECK HEATER AND REPLACE IF BLOWN. CHECK VOLTAGE AT TERMINAL STRIP IN PANEL. IF NO VOLTAGE, SEE CONTROL ADJUSTMENT INSTRUCTION UNIT D, SECTION 6.2.1 REPLACE IF DEFECTIVE.
1. 2. 2. 5.	1.2.6.4.	1.224
RUBBER BACK-UP IS CUT OR WORN HEATER BLADE IS DAMAGED HEATER BLADE IS NOT IN ALIGNMENT WITH BACK-UP OR IS SCRAPING THE JAW PLATES RUBBER GRIPPERS ON JAW PLATES ARE NOT IN ALIGNMENT WITH SOLID JAW BACK-UP HEATER IS NOT OPERABLE.	FILM FEED ROLL SET SCREW LOOSE FILM FEED ROLL DIRTY FILM FEED SPROCKET CLUTCH SLIPPING FILM FEED NYLON BRAKE NOT WORKING	BLOWN FUSE HEATER IS BLOWN HEATER CONTROL IS NOT SET PROPERLY CONTROL IS DEFFECTIVE
3	1.88.9.	1.2.64
POOR SEAL QUALITY	INCONSISTENT VERTICAL BAG DIMENSION	NO HEAT AT SILICONE BACK-UP KUBBER

IF THE PROBLEM CANNOT BE SOLVED BY THE INFORMATION IN THIS MANUAL, CONTACT RENNCO BY PHONE AND REQUEST TO TALK TO SOMEONE IN SERVICE.

UNIT G MAINTENANCE & LUBRICATION SCHEDULE

SECTION 1 RECOMMENDED MAINTENANCE FOR YOUR RENNCO PACKAGER

DAILY MAINTENANCE

1. Make sure all guards are in place

2. Check to see that safety is functioning properly

3. Wipe seal blade surfaces to remove any build-up

4. See that film guide bar is set properly

5. Make sure machine is operating smoothly and is making good seals

WEEKLY MAINTENANCE (After 40 hours)

- 1. Remove heater jaw cover and clean sealing assembly
- 2. Check the silicone gripper and replace if necessary

3. Wipe seal blade surfaces to remove any build-up

4. Insure that all nuts, bolts and heater wire are secured

5. Check trim take-up, clean (no oil or grease) and adjust if necessary

6. Make sure all cylinders are working smoothly

7. Make sure you are getting good seals and good gripping of material

SECTION 2 LUBRICATION SCHEDULE

Trim Wind-up Motor Gear Head	Yearly	SAE #50 non-detergent gear oil
Jaw Support Blocks	Weekly	Models 101 & 201, light weight grease; Model 401, light oil
Heater Guide Shaft Linear Bearing Blocks	Monthly	Light weight grease
Bronze Bushings on: Transfer Shaft	Normally None required	Light oil if required
Roller Bearings on Jaw Drive Linkage	6 months	Medium weight bearing grease (disassemble and pack)
Film Feed Sprockets	6 months	Medium weight bearing grease (disassemble and pack)
FRL Unit	As required to keep bowl filled	Mobil velocite V-6 light bodied oil or equivalent air lubricant

SPARE PARTS FOR MODEL 101, 201, 401, 501 SHRINK PACKAGERS (GE PC CONTROLLED)

QUANTITY	PART DESCRIPTION
1 1 6ft. 1/2 pt. 10 ft. 10 ft. 2 ea.	SMC Single Solenoid 4-way valve NSV 4114-0009D SMC Interface Speed Control SP0100 Omron Proximity Switch E2E-X5E1 Silicone Gripper Material Mobil V-6 light bodied oil 1/4" poly tubing 3/8" poly tubing Fuses: Model 101 - 1 amp, 5 amp, 8 amp, 15 amp Model 201 - 1 amp, 5 amp, 15 amp Model 401 - 1 amp, 5 amp, 10 amp, 15 amp Model 501 - 1 amp, 5 amp, 10 amp, 13 amp, 20 amp
5 1	Horizontal Heater Blade Vertical Heater Blade Horizontal Heater Vertical Heater Horizontal Solid Silicone Back-Up - 1/4" Square, 35 Durometer Vertical Solid Silicone Back-Up - 1/4" Square, 35 Durometer Horizontal Silicone Foam Cushion - 1/4" x 1/2" (Firm) Vertical Silicone Foam Cushion - 1/4" x 1/2" (Firm) 18 yd. roll, 10 mil x 1/4" wide teflon tape T-10

OPTIONAL

1 G/E/ series one JR programmable controller